| Basic <br> Simulation Lab Manual |  |
| :---: | :---: |
| Basic Simulation Lab with MATLAB Written for under graduate students in the fields of electronics and communication, this Manual is meant to supplement the theoretical concepts taught in an introductory course on signals and systems. Each Simulation contains all the theoretical background information needed for the simulations as well as the required MATLAB code. Topics include an introduction to vectors and matrices, operations on signals and sequences, and the Fourier transform etc. | A Guide to Student for BS LAB |

# LABORATORY MANUAL BASIC SIMULATION 

II B. TECH -I Semester (ECE-R22)


## J. B. Institute of Engineering \& Technology (UGC Autonomous)

Accredited by NAAC \& NBA, approved by AICTE \& Permanently Affiliated to JNTUH Department of Electronics \& Communication Engineering

## DEPARTMENT OF ELECTRONICS \& COMMUNICATION ENGINEERING

## VISION AND MISSION

## VISION

- To be a guiding force enabling multifarious applications in Electronics and Communications Engineering, promote innovative research in the latest technologies to meet societal needs


## MISSION

- To provide and strengthen core competencies among the students through expert training and industry interaction.
- To promote advanced designing and modeling skills to sustain technical development and lifelong learning in ECE.
- To promote social responsibility and ethical values, within and outside the department.


## PEO'S, PO'S \& PSOS

| Program Educational Objectives (PEOs): |  |
| :---: | :--- |
| PEO 1 | Practice Technical skills widely in industrial, societal and real time <br> applications. |
| PEO 2 | Engage in the pursuit of higher education, delve into extensive research <br> and development endeavours, and explore creative and innovative <br> ventures in the domains of science, engineering, technology. |
| PEO 3 | Exhibit professional ethics and moral values and capability of working <br> with professional skills to contribute towards the need of industry and <br> society. |

## PROGRAM OUTCOMES (POs)

## Engineering Graduates will be able to:

1. Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
2. Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
3. Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
4. Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
5. Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
6. The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
7. Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
8. Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of engineering practice.
9. Individual and teamwork: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
10.Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
11.Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
10. Life-long learning: Recognize the need for and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

| Program Specific Outcomes (PSOs): |  |
| :---: | :--- |
| PSO 1 | Carry out the Analysis and Design different Analog \& Digital circuits <br> with given specifications. |
| PSO 2 | Construct and test different communication systems for various <br> applications. |

## INSTRUCTIONS TO THE STUDENTS

1. Students are required to attend all labs.
2. Students will work individually in hardware laboratories and in computer laboratories.
3. While coming to the lab bring the lab manual cum observation book, record etc.
4. Take only the lab manual, calculator (if needed) and a pen or pencil to the work area.
5. Before coming to the lab, prepare the prelab questions. Read through the lab experiment to familiarize yourself with the components and assembly sequence.
6. Utilize 2 hours time properly to perform the experiment (both in software and hardware) and note down the readings properly. Do the calculations, draw the graph and take signature from the instructor.
7. If the experiment is not completed in the prescribed time, the pending work has tobe done in the leisure hour or extended hours.
8. You have to submit the completed record book according to the deadlines set up by your instructor.
9. For practical subjects there shall be a continuous evaluation during the semester for 30 sessional marks and 70 end examination marks.
10. Of the 30 marks for internal, 20 marks shall be awarded for day-to-day work and 10 marks to be awarded by conducting an internal laboratory test.

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## Basic Simulation Lab Manual <br> EXPERMENT NO:1 <br> BASIC OPERATIONS ON MATRICES

AIM: - To write a MATLAB program to perform some basic operation on matrices such as addition, subtraction, multiplication.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

MATLAB, which stands for MATRIX Laboratory, is a state-of-the-art mathematical software package, which is used extensively in both academia and industry. It is an interactive program for numerical computation and data visualization, which along with its programming capabilities provides a very useful tool for almost all areas of science and engineering. Unlike other mathematical packages, such as MAPLE or MATHEMATICA, MATLAB cannot perform symbolic manipulations without the use of additional Toolboxes. It remains however, one of the leading software packages for numerical computation.
As you might guess from its name, MATLAB deals mainly with matrices. A scalar is a 1-by-1 matrix and a row vector of length say 5, is a 1-by-5 matrix.. One of the many advantages of MATLAB is the natural notation used. It looks a lot like the notation that you encounter in a linear algebra. This makes the use of the program especially easy and it is whatmakes MATLAB a natural choice for numerical computations. The purpose of this experiment is to familiarize MATLAB, by introducing the basic features and commands of the program.

## Built in Functions:

## 1. Scalar Functions:

Certain MATLAB functions are essentially used on scalars, but operate element-wise whenapplied to a matrix (or vector). They are summarized below.

1. sin - trigonometric sine
2. cos - trigonometric cosine
3. tan-trigonometric tangent
4. asin - trigonometric inverse sine (arcsine)
5. acos - trigonometric inverse cosine (arccosine)
6. atan - trigonometric inverse tangent (arctangent)
7. exp - exponential
8. log - natural logarithm
9. abs - absolute value

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10. sqrt - square root
11. rem - remainder
12. round - round towards nearest integer
13. floor - round towards negative infinity
14. ceil - round towards positive infinity

## 2. Vector Functions:

Other MATLAB functions operate essentially on vectors returning a scalar value. Some ofthese functions are given below.

1. max largest component : get the row in which the maximum element lies
2. min smallest component
3. length length of a vector
4. sort sort in ascending order
5. sum sum of elements
6. prod product of elements
7. median median value
8. mean mean value std standard deviation

## 3. Matrix Functions:

Much of MATLAB" s power comes from its matrix functions. These can be further separatedinto two sub-categories.
The first one consists of convenient matrix building functions, some of which are givenbelow.

1. eye - identity matrix
2. zeros - matrix of zeros
3. ones - matrix of ones
4. diag - extract diagonal of a matrix or create diagonal matrices
5. triu - upper triangular part of a matrix
6. tril - lower triangular part of a matrix
7. rand - randomly generated
matrixeg:
$\operatorname{diag}([0.9092 ; 0.5163 ; 0.2661])$
ans =
0.909200
00.51630
000.2661
commands in the second sub-category of matrix functions are
8. size size of a matrix
9. det determinant of a square matrix
10. inv inverse of a matrix
11. rank rank of a matrix
12. rref reduced row echelon form
13. eig eigenvalues and eigenvectors
14. poly characteristic polynomial

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

```
clc;
```

close
all;clear
all;
a=[1 2 -9 ; 2 -1 2; 3-4 3];
b=[1 2 3; 45 6; 78 9];
$\operatorname{disp}($ 'The matrix $a=$ ');
a
disp('The matrix b= ');
b
\% to find sum of $a$ and $b$
$\mathrm{c}=\mathrm{a}+\mathrm{b}$;
disp('The sum of a and b is ');
c
$\%$ to find difference of $a$ and $b$
$d=a-b ;$
disp('The difference of a and b is ');
d
\%to find multiplication of $a$ and $b$
e=a*b;
disp('The product of a and $b$ is ');
e

## $\backslash$ <br> OUTPUT:-

The matrix

```
a=a=
    1 2 -9
    2 -1 2
    3
```

The matrix

```
b=b =
    1 2 3
    4 5 6
    7 8 9
```

The sum of a and b is $\mathrm{c}=$

| 2 | 4 | -6 |
| :---: | :---: | :--- |
| 6 | 4 | 8 |
| 10 | 4 | 12 |

The difference of a and b isd $=$

```
0 0-12
-2 -6 -4
-4 -12 -6
```

The product of a and b is $\mathrm{e}=$
$\begin{array}{lll}-54 & -60 & 66\end{array}$
$\begin{array}{lll}12 & 15 & 18\end{array}$
$\begin{array}{lll}8 & 10 & 12\end{array}$

## RESULT:-

Finding addition, subtraction, multiplication using MATLAB wasSuccessfully completed.

## VIVA QUESTIONS:-

1.Expand MATLAB?And importance of MATLAB?
2.What is clear all and close all will do?
3. What is $\operatorname{disp}()$ and input()?
4. What is the syntax to find the eigen values and eigenvectors of the matrix?
5. What is the syntax to find the rank of the matrix?
6. 6.How to determine rank of Matrix?
7. How to determine Rank of Matrix?
8. How to determine Transpose of Matrix?
9. How to determine Trace of Matrix?
10. How to determine Inverse of Matrix?

## EXERCISE PROGRAMS

1. Enter the matrix $M=[1,3,-1,6: 2,4,0,-1 ; 0,-2,3,-1 ;-1,2,-5,1]$ and $N=[-1,-3,3 ; 2,-1,6 ; 1,4,-1 ; 2,-1,2]$, perform multiplication on M and N . Can order of multiplication be switched? Why or why not?
2. Enter the matrix
$M=[1,-2,8,0]$ and $N=\left[\begin{array}{cccccc}1 & 5 & 6 & 8 ; & 5 & 6\end{array}\right]$
Perform addition on M and N and see how matlab reacts.
3. Find the transpose of null matrix using matlab
4. Write a MATLAB program to perform the division operation on the following matrixA $=[24,-30,64,-81], b=[6,5,8,9]$ and verify the result.
5. Write a matlab program to perform addition operation using $2 x 3$ matrix. Assume any numbers
6. Enter the matrix
$A=[16985 ; 93584 ; 56357]$, $\mathrm{B}=\left[\begin{array}{ll}65935 ; 65485 ; 63579\end{array}\right]$,
$C=[25934 ; 56378 ; 98654]$
Find $[(A+B)+C]^{T}$
7. Enter the matrix
$A=[16985 ; 93584 ; 56357]$, $\mathrm{B}=\left[\begin{array}{ll}6 & 5 \\ 9 & 3 \\ 5\end{array}\right.$; $65485 ; 63579$ ],
$C=[25934 ; 56378 ; 98654]$
Find $[(A-B)+C]^{-1}$
8. Write a matlab program to perform addition operation using $3 x 2$ matrix. Assume any numbers
9. Write a MATLAB program to perform the division operation on the following matrix $A=[25,-35,121,-21], b=[5,5,11,3]$ and perform the transpose function on the answer
10. Find the addition of null matrix and unity matrix of order $3 x 3$.
11. Write a MATLAB program to find rank of the matrix $A=\left[\begin{array}{ll}65935 ; 65485 ; 63579\end{array}\right]$.
12. Write a MATLAB program to find Eigen of the matrix $A=\left[\begin{array}{ll}25934 ; 56378 ; 98654] . ~\end{array}\right.$
13. Write a MATLAB program to find inverse of the matrix $A=\left[\begin{array}{ll}16985 ; 93584 ; 56357]\end{array}\right.$
14. Write a MATLAB program to find determinant of the matrixA= [1 $6985 ; 93584 ; 56357$ ].
15. Write a MATLAB program to find Transpose of the matrixA=[16985; 93584 ; 56357 ]

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16. Find the multiplication of null matrix and unity matrix of order $3 x 3$.
17. Write a matlab program to perform multiplication operation using $2 \times 3$ matrix.

Assume anynumbers.
18. Write a MATLAB program to perform the division operation on the following matrixA $=[2,-5,21,-21], b=[5,15,11,13]$.
19. Enter the matrix

C $=\left[\begin{array}{llll}5 & 9 & 3 & 4 ; 6 \\ 3 & 7 & 8 ; 8 & 6 \\ 5\end{array}\right]$
Find $[(A-B)+C]^{-1}$
20. Write a matlab program to perform division operation using $3 x 2$ matrix. Assume any numbers
21. Write a MATLAB program to perform the division operation on the following matrixA $=[5,-3,11,-1], b=[6,5,1,13]$ and perform the transpose function on the answer.
22. Find the addition of null matrix and Identity matrix of order $4 \times 4$.
23. Enter the matrix $M=[2,13,-11 ; 12,4,2 ;-2,3,-1]$ and $N=[2,-1,6 ; 1,4,-1 ; 2,-1,2]$, perform multiplication on M and N .
24. Enter the matrix $\mathrm{M}=[-2,8,0]$ and $\mathrm{N}=\left[\begin{array}{cccccc}1 & 5 & 6 & 8 ; & 5 & 6\end{array}\right]$

Perform addition and multiplication on M and N and see how matlab

5;3579],
C = [2 593 4; 5637 8; 98654 ]
Find $[(A+B)+C]^{T}$
26. Find the addition of null matrix and unity matrix of order $4 \times 4$.
27. Write a MATLAB program to find rank of the matrix $A=\left[\begin{array}{lll}64935 ; 62485 ; 63179\end{array}\right]$.
28. Write a MATLAB program to find Eigen of the matrix $A=\left[\begin{array}{lll}2 & 5 & 3\end{array} 4 ; 54378 ; 91654\right]$.
29. Write a MATLAB program to find inverse of the matrix $A=\left[\begin{array}{ll}15985 ; 43584 ; 56350]\end{array}\right.$
30. Write a MATLAB program to find determinant of the matrixA= [16 68 5; $93564 ; 16356$ ].

## Real Time application:

We see the results of matrix mathematics in every computer-generated image that has areflection, or distortion effects such as light passing through rippling water.

Basic Simulation Lab Manual
EXPERMENT NO:2

## GENERATION OF VARIOUS SIGNALS \& SEQUENCES

AIM:- To write a "MATLAB" Program to generate various signals and sequences,such as unit impulse, unit step, unit ramp, sinusoidal, square, sawtooth, triangular, sinc functions.

## SOFTWARE REQURIED:-

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY:-

One of the more useful functions in the study of linear systems is the "unit impulse function." An ideal impulse function is a function that is zero everywhere but at the origin, where it isinfinitely high. However, the area of the impulse is finite. This is, at first hard to visualize butwe can do so by using the graphs shown below.


Basic Simulation Lab Manual
Key Concept: Sifting Property of the Impulse

If $b>a$, then

$$
\int_{a}^{b} \delta(t-T) \cdot f(t) d t= \begin{cases}f(T), & a<T<b \\ 0, & \text { otherwise }\end{cases}
$$

Example: Another integral problem
Assume $\mathrm{a}<\mathrm{b}$, and evaluate the integral

$$
\int_{a}^{b} \delta(t) \cdot f(t-T) d t
$$

## Solution:

We now that the impulse is zero except at $t=0$ so

$$
\delta(t) \cdot f(t-T)=\delta(t) \cdot f(0-T)=\delta(t) \cdot f(-T)
$$

and

$$
\begin{aligned}
\int_{a}^{b} \delta(t) \cdot f(t-T) d t & =\int_{a}^{b} \delta(t) \cdot f(-T) d t \\
& =f(-T) \cdot \int_{a}^{b} \delta(t) d t \\
& =\left\{\begin{array}{cc}
f(-T), & a<0<b \\
0, & \text { otherwise }
\end{array}\right.
\end{aligned}
$$

Unit Step Function
The unit step function and the impulse function are considered to be fundamental functions in engineering, and it is strongly recommended that the reader becomes very familiar with both of these functions.

The unit step function, also known as the Heaviside function, is defined as such:

$$
u(t)= \begin{cases}0, & \text { if } t<0 \\ 1, & \text { if } t>0 \\ \frac{1}{2}, & \text { if } t=0\end{cases}
$$

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Sometimes, $u(0)$ is given other values, usually either 0 or 1 . For many applications, it isirrelevant what the value at zero is. $u(0)$ is generally written as undefined.

## Derivative

The unit step function is level in all places except for a discontinuity at $t=0$. For this reason, the derivative of the unit step function is 0 at all points $t$, except where $t=0$. Where $t=0$, the derivative of the unit step function is infinite.

The derivative of a unit step function is called an impulse function. The impulse function willbe described in more detail next.

## Integral

The integral of a unit step function is computed as such:

$$
\begin{aligned}
& \int_{-\infty}^{t} u(s) d s=\left\{\begin{array}{cc}
0, & \text { if } t<0 \\
\int_{0}^{t} d s=t, & \text { if } t \geq 0
\end{array}\right\}=t u(t) \\
& \xrightarrow[0]{u\left(t-t_{0}\right)} \\
& \begin{array}{ll}
t_{0} & t
\end{array}
\end{aligned}
$$

## Sinc Function

There is a particular form that appears so frequently in communications engineering, that we give it its own name. This function is called the "Sinc function" and is discussed below:

The Sinc function is defined as below

$$
\operatorname{sinc}(x)=\frac{\sin (\pi x)}{\pi x} \text { if } x \neq 0
$$

and $\operatorname{Sinc}(0)=1$
The value of $\operatorname{sinc}(x)$ is defined as 1 at $x=0$, since

$$
\lim _{x \rightarrow 0} \operatorname{sinc}(x)=1
$$

This fact can be proven by noting that for x near 0 ,

$$
1>\frac{\sin (x)}{x}>\cos (x)
$$

Then, since $\cos (0)=1$, we can apply the Squeeze Theorem to show that the sinc function approaches one as x goes to zero. Thus, defining $\operatorname{sinc}(0)$ to be 1 makes the sinc function continuous.

Also, the Sinc function approaches zero as x goes towards infinity, with the envelope of $\operatorname{sinc}(\mathrm{x})$ tapering off as $1 / \mathrm{x}$.

## Rect Function

The Rect Function is a function which produces a rectangular-shaped pulse with a width of 1 centered at $t=0$. The Rect function pulse also has a height of 1 . The Sinc function and the rectangular function form a Fourier transform pair.

A Rect function can be written in the form:

$$
\operatorname{rect}\left(\frac{t-X}{Y}\right)
$$

where the pulse is centered at X and has width Y . We can define the impulse function above in terms of the rectangle function by centering the pulse at zero ( $\mathrm{X}=0$ ), setting it's height to 1 /Aand setting the pulse width to A , which approaches zero:

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$$
\delta(t)=\lim _{A \rightarrow 0} \frac{1}{A} \operatorname{rect}\left(\frac{t-0}{A}\right)
$$

We can also construct a Rect function out of a pair of unit step functions

$$
\operatorname{rect}\left(\frac{t-X}{Y}\right)=u(t-X+Y / 2)-u(t-X-Y / 2)
$$

Here, both unit step functions are set a distance of $\mathrm{Y} / 2$ away from the center point of $(\mathrm{t}-\mathrm{X})$.
SAW TOOTH:-
The sawtooth wave (or saw wave) is a kind of non-sinusoidal waveform. It is named a sawtooth based on its resemblance to the teeth on the blade of a saw. The convention is that a sawtooth wave ramps upward and then sharply drops. However, there are also sawtooth waves in which the wave ramps downward and then sharply rises. The latter type of sawtooth wave is called a 'reverse sawtooth wave' or 'inverse sawtooth wave'. As audio signals, the two orientations of sawtooth wave sound identical. The piecewise linear function based on the floor function of timet, is an example of a sawtooth wave with period 1.

$$
x(t)=2\left(\frac{t}{a}-\text { floor }\left(\frac{t}{a}+\frac{1}{2}\right)\right)
$$

## Triangle wave

A triangle wave is a non-sinusoidal waveform named for its triangular shape.A bandlimited triangle wave pictured in the time domain (top) and frequency domain (bottom). The fundamental is at 220 Hz (A2).Like a square wave, the triangle wave contains only odd harmonics. However, the higher harmonics roll off much faster than in a square wave (proportional to the inverse square of the harmonic number as opposed to just the inverse).It is possible to approximate a triangle wave with additive synthesis by adding odd harmonics of the fundamental, multiplying every ( $4 n-1$ )th harmonic by -1 (or changing its phase by $\pi$ ), and rolling off the harmonics by the inverse square of their relative frequency to the fundamental.This infinite Fourier series converges to the triangle wave:

$$
\begin{aligned}
x_{\text {triangle }}(t) & =\frac{8}{\pi^{2}} \sum_{k=0}^{\infty}(-1)^{k} \frac{\sin ((2 k+1) \omega t)}{(2 k+1)^{2}} \\
& =\frac{8}{\pi^{2}}\left(\sin (\omega t)-\frac{1}{9} \sin (3 \omega t)+\frac{1}{25} \sin (5 \omega t)-\cdots\right)
\end{aligned}
$$

where $\omega$ is the angular frequency.

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## Sinusoidal Signal Generation

The sine wave or sinusoid is a mathematical function that describes a smooth repetitive oscillation. It occurs often in pure mathematics, as well as physics, signal processing, electrical engineering and many other fields. Its most basic form as a function of time $(\mathrm{t})$ is: where:

- A, the amplitude, is the peak deviation of the function from its center position.
- $\omega$, the angular frequency, specifies how many oscillations occur in a unit timeinterval, in radians per second
- $\varphi$, the phase, specifies where in its cycle the oscillation begins at $t=0 . A$ sampled sinusoid may be written as:

$$
x(n)=A \sin \left(2 \pi \frac{f}{f_{s}} n+\vartheta\right)
$$

where $f$ is the signal frequency, fs is the sampling frequency, $\theta$ is the phase and $A$ is theamplitude of the signal.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

```
%unit impulse function%clc;
clear all; close
all; t=-10:1:10;
x=(t==0);
subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');
title('unit impulse function');subplot(2,1,2);
stem(t,x,'r');
xlabel('time');
ylabel('amplitude');
title('unit impulse discreat function');
```

Basic Simulation Lab Manual
\%unit step function \%
clc;
clear all;close
all;N=100;
$\mathrm{t}=1: 100$;
$\mathrm{x}=\mathrm{ones}(1, \mathrm{~N})$;
subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');
title('unit step function');subplot(2,1,2);
stem( $\mathrm{t}, \mathrm{x}$, 'r');
xlabel('time');
ylabel('amplitude');
title('unit step discreat function');
\%unit ramp function \%clc;
clear all;
close all;
$\mathrm{t}=0$ :20;
x=t; subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');
title('unit ramp function');subplot(2,1,2);
stem( $\mathrm{t}, \mathrm{x}$, 'r');
xlabel('time');
ylabel('amplitude');
title('unit ramp discreat function');
\%sinusoidal function \%clc;
clear all; close
all; $\mathrm{t}=0: 0.01: 2$;
$\mathrm{x}=\sin \left(2^{*} \mathrm{pi}^{*} \mathrm{t}\right)$;
subplot(2,1,1);
plot(t,x,'g');
xlabel('time');

```
ylabel('amplitude'); title('sinusoidal signal');
subplot(2,1,2);
stem(t,x,'r');
xlabel('time'); ylabel('amplitude');
title('sinusoidal sequence');
%square function%clc;
clear all; close
all; t=0:0.01:2;
x=square(2*pi*t);
subplot(2,1,1);
plot(t,x,'g');
xlabel('time');
ylabel('amplitude'); title('square
signal');subplot(2,1,2);
stem(t,x,'r');
xlabel('time'); ylabel('amplitude');
title('square sequence');
%sawtooth function%clc;
clear all; close
all; t=0:0.01:2;
x=sawtooth(2* pi*5*t);
subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');
title('sawtooth signal');subplot(2,1,2);
stem(t,x,'r');
xlabel('time'); ylabel('amplitude');
title('sawtooth sequence');
```

Basic Simulation Lab Manual
\%trianguler function \%
clc;
clear all; close
all; $\mathrm{t}=0: 0.01: 2$;
$\mathrm{x}=$ sawtooth(2*pi*5*t,0.5);subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');
title('trianguler signal');subplot(2,1,2);
stem( $\mathrm{t}, \mathrm{x}$, 'r');
xlabel('time'); ylabel('amplitude');
title('trianguler sequence');
\%sinc function \%clc;
clear all;close
all;
$\mathrm{t}=$ linspace $(-5,5)$;
$\mathrm{x}=\operatorname{sinc}(\mathrm{t})$;
subplot(2,1,1);
plot(t,x,'g');
xlabel('time');
ylabel('amplitude');
title('sinc signal');
subplot(2,1,2);
stem(t,x,'r');
xlabel('time');
ylabel('amplitude'); title('sinc
sequence');

## Basic Simulation Lab Manual

## Simulations:





## Basic Simulation Lab Manual

## Unit ramp function



Sinusoidal function



## Basic Simulation Lab Manual

Square function

square sequence


Sawtooth function



## Basic Simulation Lab Manual

## Triangular function




Sinc Function


## RESULT: -

Thus the Generation of continuous time signals like unit step, sawtooth, triangular, sinusoidal, ramp and sinc functions are successfully completedby using MATLAB.

Basic Simulation Lab Manual

## VIVA QUESTIONS: -

1. Define Signal?
2. Define deterministic and Random Signal?
3. Define Delta Function?
4. What is Signal Modeling?
5. Define Periodic and a periodic Signal?
6.Write the relation between Step and Impulse signals?
6. Write the relation between Ramp and impulse signals?
7. Write the relation between Ramp and Step signals?9.Define Standard signals?
8. Give examples of Standard signals?

## EXERCISE QUESTIONS

1. Generate rectangular pulse function by using MATLAB.
2. 



Write a matlab program to get the above output where $t_{0}=2$
3. Write a program to get the result in signalr $(\mathrm{t})=\mathrm{u}(\mathrm{t})-2^{*} \mathrm{u}(\mathrm{t}+1)$
4. Write a program to get the following output $t=-1:-5$

5.


Write mat lab program to get the above outputX $(\mathrm{t})=1 ;(0<t<2)$
$=10 ;(2<t<15)$ Note: Add ramp and unit

## Basic Simulation Lab Manual

6. Write a matlab program to generate a sine wave with amplitude $=3$, frequency 20 Hz .
7. Write a matlab program to generate a cos wave with amplitude $=3$, frequency 20 Hz .
8. Write a matlab program to generate a triangular wave with amplitude $=8$, frequency 10 Hz .
9. Write a matlab program to generate a square wave with amplitude $=2$, frequency 10 kHz .
10. Write a matlab program to generate the signum function.
11. Write a matlab program to generate exponential growing signal.
12. Write a matlab program to generate exponential decaying signal.
13. Write a matlab program to generate a triangular wave with amplitude $=6$, frequency 1 Hz .
14. Write a matlab program to generate a square wave with amplitude $=5$, frequency 5 kHz .
15. Write a matlab program to generate a sawtooth wave with amplitude $=8$, frequency 5 Khz .
16. Write a matlab program to generate a sine wave with amplitude $=5$, frequency 5 Hz .
17. Write a matlab program to generate a cos wave with amplitude $=4$, frequency 10 Hz .
18. Write a matlab program to generate a triangular wave with amplitude $=5$, frequency 4 Hz .
19. Write a matlab program to generate a square wave with amplitude $=1$, frequency 20 kHz .
20. Write a matlab program to generate the signum function.
21. Wr ite a matlab program to generate a square wave with amplitude $=4$, frequency 5 kHz .
22. Write a matlab program to generate a triangular wave with amplitude $=6$, frequency 6 Hz .
23. Write a matlab program to generate a triangular wave with amplitude $=8$,frequency 2 Hz .
24. Write a matlab program to generate a square wave with amplitude $=7$, frequency 5 kHz .
25. Write a matlab program to generate a sawtooth wave with amplitude $=10$, frequency 10 Khz .
26. Write a matlab program to generate the signum function in frquency domain?.
27. Write a matlab program to generate exponential growing signal in time domain?.
28. Write a matlab program to generate exponential decaying signal in time domain?.
29. Write a matlab program to generate a triangular wave with amplitude $=4$,frequency 6 Hz .
30. Write a matlab program to generate a square wave with amplitude $=8$, frequency 4 kHz .

## Real Time Applications:

- Industrial control and automation (Control the velocity or position of an object)
- Examples: Controlling the position of a valve or shaft of a motor
- Mechanical Translational Systems
- Mechanical Rotational Systems.

Basic Simulation Lab Manual


Basic Simulation Lab Manual


Basic Simulation Lab Manual
EXPERMENT NO:3

## OPERATIONS ON SIGNALS \& SEQUENCES

AIM: -
To performs operations on signals and sequences such as addition, multiplication,scaling, shifting, folding, computation of energy and average power.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

## Basic Operation on Signals:

Time shifting: $y(t)=x(t-T)$ The effect that a time shift has on the appearance of a signallf $T$ is a positive number, the time shifted signal, $x(t-T)$ gets shifted to the right, otherwise it gets shifted left.

## Signal Shifting and Delay:



Shifting: $y(n)=\{x(n-k)\} ; m=n-k ; y=x$;
Time reversal: $\mathrm{Y}(\mathrm{t})=\mathrm{y}(-\mathrm{t})$ Time reversal _ips the signal about $\mathrm{t}=0$ as seen inFigure 1.

## Signal Addition and Subtraction:

Addition: any two signals can be added to form a third
signal, $\mathrm{z}(\mathrm{t})=\mathrm{x}(\mathrm{t})+\mathrm{y}(\mathrm{t})$
Input, $x_{1}(n)$


## Basic Simulation Lab Manual

## Signal Amplification:

Input, $x_{I}(n)$


## Multiplication/Division:

of two signals, their product is also a

Input, $\mathrm{x}_{\mathrm{l}}(\mathrm{n})$

signal. $\mathrm{z}(\mathrm{t})=\mathrm{x}(\mathrm{t}) \mathrm{y}(\mathrm{t})$

## folding:

$$
\mathrm{y}(\mathrm{n})=\{\mathrm{x}(-\mathrm{n})\} ; \mathrm{y}=\mathrm{fliplr}(\mathrm{x}) ; \mathrm{n}=-\mathrm{fliplr}(\mathrm{n}) ;
$$

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

\%Addition and multiplication of two signals\%
clc;
clear all; close all;
$\mathrm{t}=0: 0.001: 2$;
$\mathrm{s} 1=6 * \sin \left(2 *{ }^{*}{ }^{*}{ }^{*}{ }^{*} \mathrm{t}\right)$;
subplot(4,1,1);
plot(t,s1,'g');
xlabel('time');
ylabel('amplitude');

Basic Simulation Lab Manual
title('first signal'); s2=8* $\sin \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right) ; \operatorname{subplot}(4,1,2)$;
plot(t,s2,'r');
xlabel('time'); ylabel('amplitude'); title('second signal');s3=s1+s2; subplot(4,1,3); plot(t,s3,'g');
xlabel('time'); ylabel('amplitude'); title('sum of two signals');s4=s1.*s2;
subplot(4,1,4);
plot(t,s4,'g');
xlabel('time'); ylabel('amplitude');
title('multiplication of two signals');

| \%Amplitude scaling for signals\% | \%Time scaling for signals\% |
| :--- | :--- |
| clc; | clc; clear all; close all; |
| clear all; close all; t=0:0.001:2; | t=0:0.001:2; |
| s1=6*sin(2*pi*5*t);subplot(3,1,1); | s1=6*sin(2*pi*5*t); subplot(3,1,1); |
| plot(t,s1,'g'); | plot(t,s1,'g'); |
| xlabel('time'); | xlabel('time'); ylabel('amplitude'); |
| ylabel('amplitude'); | title('sinusoidal signal'); t1=3*t; |
| title('sinusoidal signal'); | subplot(3,1,2); |
| s2=3*s1; subplot(3,1,2); | plot(t1,s1,'r'); |
| plot(t,s2,'r'); | xlabel('time'); ylabel('amplitude'); |
| xlabel('time'); | title('compressed signal'); t2=t/3; |
| ylabel('amplitude'); | subplot(3,1,3); |
| title('amplified signal'); | plot(t2,s1,'g'); |
| s3=s1/3; subplot(3,1,3); | xlabel('time'); ylabel('amplitude'); |
| plot(t,s3,'g'); | title('enlarged signal'); |
| xlabel('time'); ylabel('amplitude'); |  |
| title('attenuated signal'); |  |

## Basic Simulation Lab Manual

| \%Time shifting of a signal\% | \%Time folding of a signal\% |
| :--- | :--- |
| clc; |  |
| clear all; close all; t=0:0.001:3; | clc; |
| s1=6*sin(2*pi*5*t);subplot(3,1,1); | clear all; close all; t=0:0.001:2; |
| plot(t,s1,'g'); | $\mathrm{s}=\sin \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right) ; \mathrm{m}=l \mathrm{length}(\mathrm{s}) ;$ |
| xlabel('time'); ylabel('amplitude'); | $\mathrm{n}=[-\mathrm{m}: \mathrm{m}] ;$ |
| title('sinusoidal signal');t1=t+10; | $\mathrm{y}=[0, \mathrm{zeros(1,m),s];}$ |
| subplot(3,1,2); | subplot(2,1,1); |
| plot(t1,s1,'r'); | plot(n,y,'g'); |
| xlabel('time'); ylabel('amplitude'); | xlabel('time'); ylabel('amplitude'); |
| title('right shift of the signal');t2=t-10; | title('original signal'); |
| subplot(3,1,3); | y1=[fliplr(s),0,zeros(1,m)]; |
| plot(t2,s1,'g'); | subplot(2,1,2); |
| xlabel('time'); ylabel('amplitude'); | plot(n,y1,'r'); |
| title('left shift of the signal'); | xlabel('time'); ylabel('amplitude'); |
|  | title('folded signal'); |
|  |  |

\%Time shifting of a signal\%
clc;
clear all; close all; $\mathrm{t}=0: 0.001: 3$;
$\mathrm{s} 1=6 * \sin \left(2{ }^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$;subplot( $3,1,1$ );
$\operatorname{plot}(\mathrm{t}, \mathrm{s} 1, \mathrm{~g} \mathrm{~g})$;
xlabel('time'); ylabel('amplitude');
title('sinusoidal signal');t1=t+10;
subplot(3,1,2);
plot(t1,s1,'r');
xlabel('time'); ylabel('amplitude');
title('right shift of the signal');t2=t-10;
subplot(3,1,3);
plot(t2,s1,'g');
xlabel('time'); ylabel('amplitude');
title('left shift of the signal');
\%Time folding of a signal \%clc;
clear all; close all; $\mathrm{t}=0: 0.001: 2$;
$\mathrm{s}=\sin \left(2^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$;
$\mathrm{m}=$ length(s);
$\mathrm{n}=[-\mathrm{m}: \mathrm{m}]$;
$\mathrm{y}=[0, \mathrm{zeros}(1, \mathrm{~m}), \mathrm{s}]$;
subplot(2,1,1);
plot(n,y,'g');
xlabel('time'); ylabel('amplitude');
title('original signal');
$\mathrm{y} 1=[\mathrm{fliplr}(\mathrm{s}), 0, \mathrm{zeros}(1, \mathrm{~m})]$;
subplot(2,1,2);
plot(n,y1,'r');
xlabel('time');
ylabel('amplitude');
title('folded signal');

## Basic Simulation Lab Manual

## OUTPUT: -

Addition and multiplication of two signals


## Basic Simulation Lab Manual

Amplitude scaling for signals


## Basic Simulation Lab Manual

Time scaling for signals

compressed signal



## Basic Simulation Lab Manual

Time shifting of a signal




Basic Simulation Lab Manual

Time folding of a signal


## RESULT:

In this experiment the various oprations on signals have beenPerformed Using MATLAB have been demonstrated.

## VIVA QUESTIONS: -

1. Define Symmetric and Anti-Symmetric Signals?
2. Define Continuous and Discrete Time Signals?
3. What are the Different types of representation of discrete time signals?
4. What are the Different types of Operation performed on signals?
5. What is System?
6.Explain Even Signals?
7.Explain Odd signals?
8.Define Periodic signals?
9.Define Aperiodic
signals?
10.Differentiate Energy and Power signals with examples?

## EXERCISE PROGRAMS

1. Write a MATLAB program to generate amplitude scaling of a sequence.
2. Write a MATLAB program to subtract two sinusoidal signals.
3. Write a MATLAB program to subtract and multiply two sinusoidal signals.
4. Write a MATLAB program to right shift the signal to 5 times of the original signal.
5. Write a MATLAB program to left shift the signal to 8 times of the original signal.
6. Write a MATLAB program to add two different signals with $2<t<5$
7. Write a MATLAB program to shift a positive time line signal to negative timeline signal.
8. Write a MATLAB program to subtract co-sinusoidal signals.
9. Write a MATLAB program to subtract two sinusoidal signals
10. Write a MATLAB program to division and multiply two co-sinusoidal signals.
11. Write a MATLAB program to generate time scaling of a sequence.
12. Write a MATLAB program to generate time shifting of a sequence.
13. Write a MATLAB program to generate time folding of a sequence.
14. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 5.
15. Write a MATLAB program to generate time scaling of a sequence with time 2 sec .
16. Write a MATLAB program to add two different signals with $4<t<8$
17. Write a MATLAB program to shift a negative time line signal to positive timeline signal.
18. Write a MATLAB program to subtract sinusoidal signals.
19. Write a MATLAB program to subtract and divide two sinusoidal signals
20. Write a MATLAB program to add and multiply two co-sinusoidal signals.
21. Write a MATLAB program to generate time scaling of a signal.
22. Write a MATLAB program to generate time shifting of a signal.
23. Write a MATLAB program to generate time folding of a signal.
24. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 10.

25 . Write a MATLAB program to generate time scaling of a sequence with time 5 sec .
26. Write a MATLAB program to substract two different signals with $2<t<5$
27. Write a MATLAB program to compress a positive time line signal to negative timeline signal.
28. Write a MATLAB program to positive shift in delay of co-sinusoidal signals.
29. Write a MATLAB program to subtract two signals.
30. Write a MATLAB program to multiply two co-sinusoidal signals of different amplitudelevels.

## Real Time Applications:

- Stream processing
- Block processing
- Vector processing
- Digital Signal Processing Applications.


## FINDING EVEN AND ODD \& REAL AND IMAGINARY PARTS OF SEQUENCES

AIM: -
Program for finding even and odd parts of sequences Using MATLAB Software\& Program for finding real and imaginary parts of sequences Using MATLAB Software

SOFTWARE REQURIED: -1. MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

## Even and Odd Signal

One of characteristics of signal is symmetry that may be useful for signal analysis. Even signals are symmetric around vertical axis, and Odd signals are symmetric about origin. Even Signal: A signal is referred to as an even if it is identical to its time-reversed counterparts; $\mathrm{x}(\mathrm{t})=\mathrm{x}(-\mathrm{t})$.
Odd Signal: A signal is odd if $\mathrm{x}(\mathrm{t})=-\mathrm{x}(-\mathrm{t})$.
An odd signal must be 0 at $\mathrm{t}=0$, in other words, odd signal passes the origin.
Using the definition of even and odd signal, any signal may be decomposed into a sum of its even part, $\mathrm{xe}(\mathrm{t})$, and its odd part, $\mathrm{xo}(\mathrm{t})$, as follows:

$$
\begin{gathered}
\mathrm{x}(\mathrm{t})=\mathrm{xe}(\mathrm{t})+\mathrm{xo}(\mathrm{t}) ; \\
\mathrm{x}(\mathrm{t})=1 / 2\{\mathrm{x}(\mathrm{t})+\mathrm{x}(-\mathrm{t})\}+1 / 2\{\mathrm{x}(\mathrm{t})-\mathrm{x}(-\mathrm{t})\} \text { where } \\
\mathrm{xe}(\mathrm{t})=1 / 2\{\mathrm{x}(\mathrm{t})+\mathrm{x}(-\mathrm{t})\} \& \mathrm{xo}(\mathrm{t})=1 / 2\{\mathrm{x}(\mathrm{t})-\mathrm{x}(-\mathrm{t})\}
\end{gathered}
$$

It is an important fact because it is relative concept of Fourier series. In Fourier series, a periodic signal can be broken into a sum of sine and cosine signals. Notice that sine function is odd signal and cosine function is even signal.

## ENERGY AND POWER SIGNAL:

A signal can be categorized into energy signal or power
signal: An energy signal has a finite energy, $0<\mathrm{E}<\infty$. In other words, energy signals have values only in the limited time duration. For example, a signal having only one square pulse is energy signal. A signal that decays exponentially has finite energy, so, itis also an energy signal. The power of an energy signal is 0 , because of dividing finite energy by infinite time (or length).

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If $x(t)$ is a real-valued signal with Fourier transform $X(f)$, and $\mathrm{u}(f)$ is the Heaviside step function, then the function:

$$
\begin{aligned}
X_{\mathrm{a}}(f) & \stackrel{\text { def }}{=} \begin{cases}2 X(f), & \text { for } f>0, \\
X(f), & \text { for } f=0, \\
0, & \text { for } f<0,\end{cases} \\
& =X(f) \cdot \underbrace{2 \mathrm{u}(f)}_{1+\operatorname{sgn}(f)}=X(f)+X(f) \cdot \operatorname{sgn}(f)
\end{aligned}
$$


contains only the non-negative frequency components of $X(f)$. And the operation is reversible, due to the Hermitian property of $X(f)$ :

$$
\begin{aligned}
X(f) & = \begin{cases}\frac{1}{2} X_{\mathrm{a}}(f), & \text { for } f>0, \\
X_{\mathrm{a}}(f) & \text { for } f=0 \\
\frac{1}{2} X_{\mathrm{a}}(-f)^{*}, & \text { for } f<0\end{cases} \\
& =\frac{1}{2}\left(X_{\mathrm{a}}(f)+X_{\mathrm{a}}(-f)^{*}\right) .
\end{aligned}
$$

$X(f)^{*}$ denotes the complex conjugate of $X(f)$.

Basic Simulation Lab Manual
The inverse Fourier transform of $X_{\mathrm{a}}(f)$ is the analytic signal:

$$
\begin{aligned}
x_{\mathrm{a}}(t) & =\mathcal{F}^{-1}\{X(f)+X(f) \cdot \operatorname{sgn}(f)\} \\
& =\mathcal{F}^{-1}\{X(f)\}+\underbrace{\mathcal{F}^{-1}\{X(f)\} * \mathcal{F}^{-1}\{\operatorname{sgn}(f)\}}_{\text {convolution }} \\
& =x(t)+j\left[x(t) * \frac{1}{\pi t}\right]
\end{aligned}
$$

where $x^{\wedge}(t)$ is the Hilbert transform of $x(t)$ and $J$ is the imaginary unit.

## PROCEDURE: -

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window

PROGRAM: -

| \%Even, odd, real, imaginary parts <br> of a sequences\% <br> clc; | \%odd part of sequence\% |
| :--- | :--- |
| clear all; |  |
| close all; | xodd=(x-xmir)/2; subplot(4,1,4); |
| h=input('enter no.of samples'); | stem(n,xodd,'g'); |
| m=(h-1)/2; | title('odd part of sequence'); |
| n=-m:m; |  |
| x=input('enter sample values'); | \%Real\&Imaginary parts of a sequences\% |
| subplot(4,1,1); | clc; |
| stem(n,x,'g'); | clear all; close all; |
| xlabel('time'); ylabel('amplitude'); | y=input('enter complex numbers'); |
| title('original sequence'); | yreal=real(y); |
| xmir=fliplr(x); subplot(4,1,2); | disp('real values of y'); yreal |
| stem(n,xmir,'r'); | yimag=imag(y); |
| xlabel('time'); ylabel('amplitude'); | disp('imaginary values of y'); |
| title('folded sequence'); | yimag |
| \%even part of sequence\% |  |
| xeven=(x+xmir)/2; subplot(4,1,3); |  |
| stem(n,xeven,'r'); |  |
| xlabel('time'); ylabel('amplitude'); |  |
| title('even part of sequence'); |  |

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## OUTPUT:-

Even,odd,real,imaginary parts of a
sequencesenter no.of samples5
enter sample values[1 234 5]


Real \& Imaginary parts of a sequences
enter complex numbers [1+6i 2-5i $34+3 i$
5i]real values of $y$
yreal =1 $\begin{array}{lllll}1 & 2 & 3 & 4\end{array} 0$ imaginary values of $y$
yimag $=$
$\begin{array}{lllll}6 & -5 & 0 & 3 & 5\end{array}$

## RESULT: -

In this experiment even and odd parts of various signals and energyand power of signals have been calculated Using MATLAB.

Basic Simulation Lab Manual


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## VIVA QUESTIONS

1. What is the formula to find odd part of signal?
2. What is Even Signal?
3. What is Odd Signal?
4. What is the formula to find even part of signal?
5. What is the difference b/w stem\&plot?
6.What is Energy Signals?
7.What is Power signals?

Define Systems?
9.How to determine time period of Periodic
signals?10.Define Frequency of signals?

## EXERCISE PROGRAM

1.Write a MATLAB program to find even part of a signal by considering 10 input samples.
2. Write a MATLAB program to find odd part of a signal by considering atleast 7 samples.
3. Write a MATLAB program to add even an odd part of a signal and see how matlab reacts forthe above program.
4. Write a matlab program to get the out put as $[-5,3,0,8]$ as imaginary values and [2 4680 ] as real values.
5. Write a MATLAB program to subtract even an odd part of a signal and see how matlab reactsfor the above program.
6. Write a MATLAB program to find real \& imaginary values of complex numbers [1+6i 2-5i 34+3i 5i].
7. Write a MATLAB program to find real \& imaginary values of complex numbers [2+6i 7+5i3 9+3i 5i].
8. Write a MATLAB program to find real \& imaginary values of complex numbers [7+6i 2-5i 38+3i 7i].
9. Write a MATLAB program to find even \& odd part of the sequence [5 632347 ].
10. Write a MATLAB program to find even \& odd part of the sequence [7 5867 7.
11.Write a MATLAB program to find even part of a signal by considering 8 input samples.
12. Write a MATLAB program to find odd part of a signal by considering 10 samples.
13. Write a MATLAB program to multiply even and odd part of a signal and see how matlabreacts for the above program.
14. Write a matlab program to get the output as $[2,5,-1,6]$ imaginary values and [ $4,2,8,0]$ asreal values.
15. Write a MATLAB program to divide even an odd part of a signal and see how matlab reactsfor the above program.
16. Write a MATLAB program to find real \& imaginary values of complex numbers
[2+4i 1-6i4+2i 8i].
17. Write a MATLAB program to find real \& imaginary values of complex numbers [4+8i 6+4i2 6+4i 6i].
18. Write a MATLAB program to find real \& imaginary values of complex numbers
[4+4i 2-5i 46+4i 6i].
19. Write a MATLAB program to find even \& odd part of the sequence [4984321].
20. Write a MATLAB program to find even \& odd part of the sequence [5 7678 ].
21. Write a MATLAB program to find even \& odd part of the sequence [ 236343 7].
22. Write a MATLAB program to find even \& odd part of the sequence [5 4686 ].
23.Write a MATLAB program to find even part of a signal by considering 6 input samples.
24. Write a MATLAB program to find odd part of a signal by considering 9 samples.
25. Write a matlab program to get the output as $[2,4,-6,8]$ imaginary values and [1, 5, 9, 3] asreal values.
26.Write a MATLAB program to find even \& odd part of the sequence [4 632634 7].
10. Write a MATLAB program to find even \& odd part of the sequence [75 5864217 ].
11.Write a MATLAB program to find even part of a signal by considering 10 input samples.
12. Write a MATLAB program to find odd part of a signal by considering 10 input samples.
13. Write a MATLAB program to multiply even and odd part of a signal.

## Real Time Applications:

- Synthesis and manipulation: E.g. speech synthesis, music synthesis, graphics.
- Analysis: Seismic data, atmospheric data, stock market analysis.
- Medical Applications.


## Linear Convolution

AIM: -
To find the output with linear convolution operation Using MATLAB Software.

## SOFTWARE REQURIED:-

1.MATLAB R2010a.
2.Windows XP SP2.

THEORY:-
Linear Convolution involves the following operations.

1. Folding
2. Multiplication
3. Addition
4. Shifting

These operations can be represented by a Mathematical Expression as follows:

$$
y[n]=\sum_{k=-\infty} x[k] /[n-k]
$$

$\mathrm{x}[\mathrm{n}]=$ Input signal Samples
$\mathrm{h}[\mathrm{n}-\mathrm{k}]=$ Impulse response co-
efficient.y[n]= Convolution output.
$\mathrm{n}=$ No. of Input samples
$\mathrm{h}=$ No. of Impulse response co-efficient.
Example : $\mathrm{X}(\mathrm{n})=\left\{\begin{array}{lllll}1 & 2 & -1 & 0 & 1\end{array}\right\}$, $\mathrm{h}(\mathrm{n})=\{1,2,3,-1\}$.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window

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```
PROGRAM:-
```


## \%Convolution of two

```
signals\%
clc;
clear all;
close all; t=0:0.001:10;
\(\mathrm{x}=\sin (\mathrm{t})\); \(\mathrm{h}=\) square \((\mathrm{t})\); subplot \((3,1,1)\);
plot(t, x,'g');
xlabel('time');
ylabel('amplitude');
title('sinusoidal
signal');
subplot(3,1,2);
plot(t,h,'r');
xlabel('time');
ylabel('amplitude');
title('square
function');
\(\mathrm{y}=\operatorname{conv}(\mathrm{x}, \mathrm{h})\);
subplot(3,1,3); plot(y); xlabel('time'); ylabel('amplitude');
title('convolution signal');
\%Convolution of two sequences\%
clc;
clear all;
close all;
\(\mathrm{L}=\) input('enter the length of 1st
sequence'); \(\mathrm{M}=\mathrm{input}(\) 'enter the length of
2nd sequence');x=input('enter the first
sequence:x(n)='); h=input('enter the
second sequence:y(n)='); \(\mathrm{N}=0:(\mathrm{L}+\mathrm{M}-1)\);
\(\mathrm{y}=\operatorname{conv}(\mathrm{x}, \mathrm{h})\);
subplot(3,1,1);
stem(x,'g');
xlabel('discrete
time');ylabel('x(n)');
title('1st sequence');
subplot(3,1,2);
stem(h,'r'); xlabel('discrete time');
```

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ylabel('h(n)'); title('second sequence');subplot(3,1,3);
stem(y); xlabel('discrete time');ylabel('y(n)');
title('convolution of two sequences');

## OUTPUT:-

Convolution of two signals


## Convolution of two sequences

enter the length of 1 st sequence 4 enter the length of $2 n d$ sequence 4 enter the first sequence: $x(n)=\left[\begin{array}{lll}1 & 2 & 3\end{array}\right]$
enter the second sequence:y(n)=[11 2334$]$


## RESULT:-

In this experiment convolution of various signals have beenperformed Using MATLAB.

Basic Simulation Lab Manual


## VIVA QUESTIONS: -

1. Define Convolution?
2. Define Properties of Convolution?
3. What is the Difference Between Convolution\& Correlation?
4. What are Dirchlet Conditions of Fourier

Series?5.What is Half Wave Symmetry?
6. Define Linear Convolution?
7. Define Properties of Convolution in time domain?
8. What is the Difference Between Linear Convolution\& Circular Correlation?
9. What are Dirchlet Conditions for Fourier

Transform?10.What is Full Wave Symmetry?

## EXERCISE PROGRAMS

1.Write the MATLAB program to perform convolution between the following sequences $X(n)=\left[\begin{array}{lll}1 & -1 & 4\end{array}\right], h(n)=\left[\begin{array}{llll}-1 & 2 & -3 & 1\end{array}\right]$.
2. Write a mat lab program to perform the convolution between sinusoidal and ramp function andsee how mat lab reacts to it.
3. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
4. Write a MATLAB program to perform convolution between sinusoidal and ramp signal andsee how mat lab reacts to it.
5. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 2 & 3\end{array} 5\right]$ and $y(n)=[-1-2]$ and see how matlab reacts to it.
6. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}1 & -3\end{array}\right]$ and $y(n)=\left[\begin{array}{llll}1 & 2 & 3 & 4\end{array}\right]$ and see how matlab reacts to it.
7. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 0 & 1\end{array} 1\right]$ and $\mathrm{y}(\mathrm{n})=\left[\begin{array}{llll}1 & 0 & 0 & 0\end{array}\right]$ and see how matlab reacts to it.
8. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lllll}1 & 1 & 1 & 0 & 0\end{array} 00\right.$ 0 and $y(n)=\left[\begin{array}{lllll}1 & 0 & 1 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
9.Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array} 0\right]$ and $y(n)=\left[\begin{array}{lll}1 & 1 & 1\end{array} 1\right]$ and see how matlab reacts to it.
10. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}6 \\ 7 & 8 \\ \text { 10 }\end{array}\right.$ ] and $y(n)=\left[\begin{array}{lll}5 & 4 & 2\end{array} 1\right]$ and see how matlab reacts to it.
11. Write the MATLAB program to perform convolution between the following sequences $X(n)=\left[\begin{array}{lll}2 & -2 & 3\end{array}\right], h(n)=\left[\begin{array}{lll}-2 & 4 & -5\end{array}\right]$.
12. Write a mat lab program to perform the convolution between step and ramp function and seehow mat lab reacts to it.
13. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
14. Write a MATLAB program to perform convolution between sinusoidal and square signal andsee how mat lab reacts to it.
15. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 3 & 4\end{array}\right]$ and $y(n)=\left[\begin{array}{ll}-2 & -4\end{array}\right]$ and see how matlab reacts to it.
16. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}3 & -4\end{array}\right]$ and $y(n)=\left[\begin{array}{lll}2 & 6 & 6\end{array}\right]$ and see how matlab reacts to it.
17. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}3 & 1 & 2\end{array} 0\right]$ and $\mathrm{y}(\mathrm{n})=\left[\begin{array}{lll}2 & 4 & 3\end{array} \mathrm{5}\right.$ ] and see how matlab reacts to it.
18. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}2 & 102110\end{array}\right]$ and $y(n)=\left[\begin{array}{llllll}1 & 1 & 1 & 2 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
19. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 1 & 2\end{array} 1\right]$ and $y(n)=\left[\begin{array}{lll}1 & 2 & 1\end{array} 2\right]$ and see how matlab reacts to it.
20. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}5 & 6 & 9 \\ 8 & 7\end{array}\right]$ and $y(n)=\left[\begin{array}{llll}1 & 2 & 3 & 2\end{array}\right]$ and see how matlab reacts to it.
21. Write the MATLAB program to perform convolution between the following sequences $X(n)=\left[\begin{array}{lll}4 & -6 & 5\end{array}\right], h(n)=\left[\begin{array}{lll}-1 & 3 & -4\end{array}\right]$.
22. Write a mat lab program to perform the convolution between ramp and step function and seehow mat lab reacts to it.
23. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
24. Write a MATLAB program to perform convolution between sinusoidal and step signal andsee how mat lab reacts to it.
25. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 5 & 6\end{array}\right]$ and $y(n)=[-3-6]$ and see how matlab reacts to it.
26. Write a MATLAB program to perform the Circular Convolution between $X(n)=\left[\begin{array}{llll}1 & 0 & 1 & 1\end{array}\right]$ and $y(n)=\left[\begin{array}{llll}1 & 0 & 0 & 0\end{array} 01\right]$ and see how matlab reacts to it.
27. Write a MATLAB program to perform the Circular Convolution between
$\mathrm{X}(\mathrm{n})=\left[\begin{array}{llllll}1 & 1 & 1 & 1 & 0 & 0\end{array} 000\right.$ ] and $\mathrm{y}(\mathrm{n})=\left[\begin{array}{lllll}1 & 0 & 1 & 0 & 1\end{array} 0100\right]$ and see how matlab reacts to it.
28. Write a MATLAB program to perform the Circular Convolution between $X(n)=\left[\begin{array}{llll}1 & 1 & 0 & 0\end{array}\right]$ and $y(n)=\left[\begin{array}{lll}1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.
29. Write a MATLAB program to perform the Circular Convolution between $\mathrm{X}(\mathrm{n})=\left[\begin{array}{lll}6 & 7 & 9\end{array} 10\right]$ and $\mathrm{y}(\mathrm{n})=\left[\begin{array}{lll}5 & 4 & 2\end{array} 1\right]$ and see how matlab reacts to it.
30. Write the MATLAB program to perform Circular Convolution between the following sequences $X(n)=\left[\begin{array}{llll}2 & -2 & 3 & 2\end{array}\right], h(n)=\left[\begin{array}{lll}-2 & 4 & -5\end{array} 2\right]$.

## Real Time Applications:

- The convolution is to determine the response $y[n]$ of a system of a known impulseresponse $h[n]$ for a given input signal $x[n]$ to obtain $y[n]$.
- Digital Image Processing Applications such as Compression and Restoration.

Basic Simulation Lab Manual
EXPERMENT NO: 6

## Auto correlation and cross correlation between Signals and sequences

AIM: -
To compute auto correlation and cross correlation between signals and Sequences.

## SOFTWARE REQURIED: -

1. MATLAB R2010a.
2.Windows XP SP2.

## THEORY:-

In Signal processing, When the autocorrelation function is normalized by mean and variance, it is sometimes referred to as the autocorrelation coefficient. Given a signal $f(t)$, the continuous autocorrelation $\operatorname{Rff}(\mathrm{T})$ is most often defined as the continuous crosscorrelation integral of $\mathrm{f}(\mathrm{t})$ with itself, at lag T

$$
R_{f f}(\tau)=(f(t) * \bar{f}(-t))(\tau)=\int_{-\infty}^{\infty} f(t+\tau) \bar{f}(t) \mathrm{d} t=\int_{-\infty}^{\infty} f(t) \bar{f}(t-\tau) \mathrm{d} t
$$

The discrete autocorrelation Rat lag $j$ for a discrete signal $x(n)$ is

$$
R_{x x}(j)=\sum_{n} x_{n} \bar{x}_{n-j}
$$

In signal processing, cross-correlation is a measure of similarity of two waveforms as a function of a time-lag applied to one of them. This is also known as a sliding dot product or sliding inner- product. It is commonly used for searching a long signal for a shorter, known feature. It has applications in pattern recognition, single particle analysis, electron tomographic averaging, cryptanalysis, and neurophysiology.

For continuous functions $f$ and $g$, the cross-correlation is defined as:

$$
(f \star g)(\tau) \stackrel{\text { def }}{=} \int_{-\infty}^{\infty} f^{*}(t) g(t+\tau) d t
$$

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where $f^{*}$ denotes the complex conjugate of $f$ and $t$ is the time lag.
Similarly, for discrete functions, the cross-correlation is defined as:

$$
(f \star g)[n] \stackrel{\text { def }}{=} \sum_{m=-\infty}^{\infty} f^{*}[m] g[m+n] .
$$

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

\%Auto correlation for a
signal\%
clc;
clear all;
close all; $\mathrm{t}=0: 0.001: 1$;
$\mathrm{x}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 3^{*} \mathrm{t}\right) ; \mathrm{a}=\mathrm{xcorr}(\mathrm{x})$; subplot(2,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');title('input signal');subplot(2,1,2);
plot(a,'r');
xlabel('time'); ylabel('amplitude');
title('auto correlation signal');

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\%cross correlation for a signal\%
clc; clear all;close all;
$\mathrm{t}=0: 0.001: 1$;
$\mathrm{x}=\cos \left(2^{*} \mathrm{pi}^{*} 3^{*} \mathrm{t}\right) ; \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right) ; \mathrm{a}=\mathrm{x} \operatorname{corr}(\mathrm{x}, \mathrm{y})$;
subplot(3,1,1);
plot(t,x,'g');
xlabel('time'); ylabel('amplitude');title('1st signal'); subplot(3,1,2);
plot(t,y,'r');
xlabel('time'); ylabel('amplitude');title('2nd signal'); subplot(3,1,3); plot(a,'r');
xlabel('time'); ylabel('amplitude');
title('cross correlation signal');
\%Auto correlation for a sequence\%clc;
clear
all;close
all;
x=input('enter sample
values') $\mathrm{a}=\mathrm{xcorr}(\mathrm{x})$;
subplot(2,1,1);
stem(x,'g');
xlabel('time');
ylabel('amplitude');
title('input
sequence');
subplot(2,1,2);
stem(a,'r');
xlabel('time'); ylabel('amplitude');
title('auto correlation sequence');

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\%cross correlation for asequence\%
clc;
clear
all;close
all;
$\mathrm{x}=\mathrm{inp} 4 \mathrm{t}($ 'enter first sequence'); $\mathrm{y}=$ input('enter second sequence');a=xcorr(x,y); subplot(3,1,1);
stem(x,'g');
xlabel('time'); ylabel('amplitude');title('1st sequence');subplot(3,1,2);
stem(y,'r');
xlabel('time'); ylabel('amplitude'); title('2nd sequence');subplot(3,1,3);
stem(a,'r');
xlabel('time'); ylabel('amplitude');
title('cross correlation sequence');

## OUTPUT:-

Auto correlation for a signal


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cross correlation for a signal


Auto correlation for a sequence
enter sample values [1 23 4 4]
$\mathrm{x}=$
$\begin{array}{llll}1 & 2 & 3 & 4\end{array}$

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cross correlation for two sequences



cross correlation sequence


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## PROGRAM:

clc; clear all; close all; t=0:0.01:1;
f1=3;
$\mathrm{x} 1=\sin \left(2^{*} \mathbf{p i}^{*} \mathbf{f} 1^{*} \mathrm{t}\right)$; figure; subplot(2,1,1); plot(t,x1); title('sine wave'); xlabel('time>');
ylabel('amplitude>');
grid;
[rxx lag1]=xcorr(x1); subplot(2,1,2); plot(lag1,rxx); grid;
title('auto-correlation
function of sine wave');
figure;
subplot(2,2,1);
plot(t,x1);
title('sine wave $x 1$ ');
xlabel('time>');
ylabel('amplitude>');
grid; f2=2;
$\mathbf{x} 2=\sin \left(2^{*} \mathbf{p i}^{*}{ }^{\mathbf{f}}{ }^{*}\right.$ t $)$;
subplot $(2,2,2)$;
plot(t,x2);
title('sine wave $x 2$ ');
xlabel('time ---->');,
ylabel('amplitude>');
grid;
[cxx lag2]=xcorr(x1,x2);
subplot(2,2,[3,4]);
plot(lag2,cxx);
grid;
title('cross-correlation function of sine wave');


## RESULT: -

In this experiment correlation of various signals have been performed UsingMATLAB.

## VIVA QUESTIONS: -

1. Define Correlation?
2. Define Auto-Correlation?
3. Define Cross-Correlation?
4. What is the importance of correlation?
5. What is the difference b/w correlation and convolution?
6. Explain two Properties of Auto-Correlation?
7. Explain two Properties of Cross-Correlation?
8. What is the difference b/w Auto-correlation and CrossCorrelation?9.Define ESD?
10.Define PSD?

## EXERCISE PROGRAMS

1. Write a MATLAB program to compute auto correlation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 15^{*} \mathrm{t}\right)$.
2. Write a MATLAB program to compute cross correlation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 7^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{p} \mathrm{i}^{*} 14^{*} \mathrm{t}\right)$.
3. Write a MATLAB program to compute the cross correleation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 15^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 3 times and verify how matlab reacts to it.
4. Write a MATLAB program to compute the auto correleation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}^{*} 15^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 2 times and verify how matlab reacts to it.
5. Write a MATLAB program to compute auto correlation between $\mathrm{x}=\sin \left(2{ }^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$, $y=\sin \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
6. Write a MATLAB program to compute cross correlation between $\mathrm{x}=\sin \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right)$, $y=\cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
7.Write a MATLAB program to compute cross correlation between two signals $\mathrm{x}=9 * \cos \left(2^{*} \mathrm{pi}^{*} 7^{*} \mathrm{t}\right), \mathrm{y}=5^{*} \cos \left(2 * \mathrm{pi}^{*} 14^{*} \mathrm{t}\right)$.

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8. Write a MATLAB program to compute cross correlation between two Sequences [1 23 45] \&[9 876 5].
9. Write a MATLAB program to compute auto correlation between two signals $\mathrm{x}=9 * \cos \left(2^{*} \mathrm{pi}^{*} 7^{*} \mathrm{t}\right), \mathrm{y}=5 * \cos \left(2 * \mathrm{pi}^{*} 14^{*} \mathrm{t}\right)$.
10. Write a MATLAB program to compute auto correlation between two Sequences

11. Write a MATLAB program to compute auto correlation between signals and Sequences. $x=\cos \left(2^{*} \mathrm{pi}^{*} 20^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right)$.
12. Write a MATLAB program to compute cross correlation between signals and Sequences. $\mathrm{x}=\cos \left(4^{*} \mathrm{pi}{ }^{*} 8^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(4^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right)$.
13. Write a MATLAB program to compute the cross correleation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}^{*} 20^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 2 times and verify how matlab reacts to it.
14. Write a MATLAB program to compute the auto correleation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi} \mathrm{i}^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 20^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 4 times and verify how matlab reacts to it.
15. Write a MATLAB program to compute auto correlation between $\mathrm{x}=\sin \left(2{ }^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right), \mathrm{y}=$ $\sin \left(4^{*} \mathrm{pi}^{*} 20^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
16. Write a MATLAB program to compute cross correlation between $\mathrm{x}=\sin \left(3^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right), \mathrm{y}=$ $\cos \left(4^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
17. Write a MATLAB program to compute cross correlation between two signals $\mathrm{x}=4^{*} \cos \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right), \mathrm{y}=6^{*} \cos \left(2^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right)$.
18. Write a MATLAB program to compute cross correlation between two Sequences [2 648 5] \& [89675].
19. Write a MATLAB program to compute auto correlation between two signals $\mathrm{x}=5^{*} \cos \left(2^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=5^{*} \cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$.
20. Write a MATLAB program to compute auto correlation between two Sequences [1 144 5] \& [99755].
21. Write a MATLAB program to compute auto correlation between signals and Sequences. $x=\cos \left(3^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(4^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right)$.

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22. Write a MATLAB program to compute cross correlation between signals and Sequences. $\mathrm{x}=\cos \left(6^{*} \mathrm{pi}^{*} 6^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(4^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$.
23. Write a MATLAB program to compute the cross correleation between signals and Sequences. $\mathrm{x}=\cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 3 times and verify how matlab reacts to it.
24. Write a MATLAB program to compute the auto correleation between signals and Sequences. $\mathrm{x}=\cos \left(4^{*} \mathrm{pi} \mathrm{i}^{*} \mathrm{t}\right), \mathrm{y}=\cos \left(2^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right)$ by increasing the amplitude of the signal by 4 times and verify how matlab reacts to it.
25. Write a MATLAB program to compute auto correlation between $\mathrm{x}=\sin \left(4^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right), \mathrm{y}=$ $\sin \left(4^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
26. Write a MATLAB program to compute auto correlation between $\mathrm{x}=\sin \left(4^{*} \mathrm{pi}^{*} 2^{*} \mathrm{t}\right), \mathrm{y}=$ $\sin \left(4^{*} \mathrm{pi}^{*} 20^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
27. Write a MATLAB program to compute cross correlation between $\mathrm{x}=\sin \left(3^{*} \mathrm{pi}^{*} 2^{*} \mathrm{t}\right), \mathrm{y}=$ $\cos \left(5^{*} \mathrm{pi}{ }^{*} 5^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
28. Write a MATLAB program to compute auto correlation between two signals $\mathrm{x}=4^{*} \cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=6^{*} \cos \left(6^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$.
29. Write a MATLAB program to compute cross correlation between two Sequences [2648 5] \& [8 967 5].
30. Write a MATLAB program to compute auto correlation between two signals $\mathrm{x}=5^{*} \cos \left(8^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=6^{*} \cos \left(7^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$.

## Real Time Applications:

- Correlation is used to extract second (and higher) order statistics from any randomsignal.
- Explains Energy and Power of Continuous and discrete systems.

Basic Simulation Lab Manual

## EXPERMENT NO:7

## Verification of linearity and time invariance properties of a given continuous /discrete system.

AIM: -
To compute linearity and time invariance properties of a given continuous /discrete System.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

THEORY:-

## LINEARITY PROPERTY

a) Homogeneity
b) Superposition

$$
\begin{aligned}
& \text { satisfies the principle of superposition } \\
& L\left[a_{1} x_{1}(n)+a_{2} x_{2}(n)\right]=a_{1} L\left[x_{1}(n)\right]+a_{2} L\left[x_{2}(n)\right] \\
& \forall a_{1}, a_{2}, x_{1}(n), x_{2}(n)
\end{aligned}
$$

The output $\mathrm{y}(\mathrm{n})$ of a linear system to an arbitrary input $\mathrm{x}(\mathrm{n})$

$$
y(n)=L[x(n)]=L\left[\sum_{n=-\infty}^{+\infty} x(k) \delta(n-k)\right]=\sum_{n=-\infty}^{+\infty} x(k) L[\delta(n-k)]
$$

$L[\delta(n-k)]$ is called impulse response, and is denoted by $h(n, k)$

$$
y(n)=\sum_{n=-\infty}^{+\infty} x(k) h(n, k)
$$

## Basic Simulation Lab Manual

## LINEAR TIME INVARIENT SYSTEMS(LTI)

A linear system in which an mput-output pair is invariant to a shift $\mathbf{n}$ in time is called a linear times-invariant system
$\mathrm{y}(\mathrm{n})=\mathrm{L}[\mathrm{x}(\mathbf{n})] \rightarrow \mathrm{y}(\mathbf{n}-\mathrm{k})=\mathrm{L}[\mathrm{x}(\mathbf{n}-\mathrm{k})]$

$$
h(n, k)=L[\delta(n-k)]=h(n-k)
$$

The output of a LTI system is call a linear convolution sum

$$
y(n)=L T I[x(n)]=\sum_{k=-\infty}^{+\infty} x(k) k(n-k) \stackrel{\Delta}{=} x(n) * h(n)
$$

An LTI system is completely characterized in the time domain by the impulse response $h(n)$.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## Basic Simulation Lab Manual

PROGRAM: -
\%Program1:\%
clc;
clear all; close all;
$\mathrm{n}=0: 40 ; \mathrm{a}=2 ; \mathrm{b}=1$;
$\mathrm{x} 1=\cos \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right)$;
$\mathrm{x} 2=\cos \left(2^{*} \mathrm{pi}^{*} 0.4^{*} \mathrm{n}\right)$;
$\mathrm{x}=\mathrm{a} * \mathrm{x} 1+\mathrm{b}^{*} \mathrm{x} 2$;
$\mathrm{y}=\mathrm{n} .{ }^{*} \mathrm{x}$;
$\mathrm{y} 1=\mathrm{n} .{ }^{*} \mathrm{x} 1$;
y2=n. ${ }^{*}$ 2;
$\mathrm{yt}=\mathrm{a}^{*} \mathrm{y} 1+\mathrm{b}^{*} \mathrm{y} 2$;
d=y-yt;
$\mathrm{d}=$ round(d)
if $d$
disp('Given system is not satisfy linearity property'); else
disp('Given system is satisfy
linearity property');
end
subplot( $3,1,1$ ), stem( $n, y$ ); grid;
subplot(3,1,2), stem(n,yt); grid;
subplot(3,1,3), stem(n,d); grid;


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```
%Program2:%
clc;
clear all; close all;
n=0:40;
a=2; b=-3;
x1=cos(2*pi*0.1*n);
x2=cos(2*pi*0.4*n);
x=a*x1+b*x2;
y=x.^2;
y1=x1.^2;
y2=x2.^2;
yt=a*y1+b*y2;
d=y-yt;
d=round(d);
if d
disp('Given system is
not satisfy linearity
property'); else
disp('Given system is
satisfy linearity
property'); end
subplot(3,1,1),
stem(n,y); grid;
subplot(3,1,2),
stem(n,yt); grid;
subplot(3,1,3),
stem(n,d);
grid;
```



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| \%Program3:\% <br> clc; <br> close all; clear all; n=0:40; D=10; <br> $\mathrm{x}=3^{*} \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right)$ - <br> $2^{*} \cos \left(2^{*} \mathrm{pi}^{*} 0.4^{*} \mathrm{n}\right)$; <br> $\mathrm{xd}=[\operatorname{zeros}(1, \mathrm{D}) \mathrm{x}]$; <br> $\mathrm{y}=\mathrm{n} .{ }^{*} \mathrm{xd}(\mathrm{n}+\mathrm{D})$; <br> $\mathrm{n} 1=\mathrm{n}+\mathrm{D}$; <br> $y d=n 1 .{ }^{*} x ; d=y-y d ;$ <br> if $d$ <br> disp('Given system is <br> not satisfy time <br> shifting property'); <br> else <br> disp('Given system is satisfy time shifting property'); end subplot( $3,1,1$ ), stem(y), <br> grid; <br> subplot(3,1,2), <br> stem(yd), <br> grid; <br> subplot(3,1,3), <br> stem(d), <br> grid; |  |
| :---: | :---: |

## VIVA QUESTIONS: -

1. Define Systems?
2. What is LTI Systems?
3. Describe LTV Systems?
4. What is the importance of Linear Systems?
5. What is the difference b/w Linear and Non-Linear Systems?
6. Explain two Properties of LTI Systems?
7. Explain two Properties of LTV Systems?
8. What is the Superposition Principal?
9.What is Difference between CT and DT systems?10.Define Causality of LTI Systems?

## EXSERCISE QUESTIONS

1. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}^{*} 2^{*} \mathrm{n}\right)$, and chech whether it satisfies the linearity property or not.
2. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2 *{ }^{*} i^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} \mathrm{pi}^{*} 2 * \mathrm{n}\right)$, and chech whether it satisfies the linearity property or not
3. Write a MATLAB program to verify the linearity prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}^{*} 0.3^{*} \mathrm{n}\right)$, and chech whether it satisfies the linearity property or not
4. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} n\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}^{*} 2^{*} \mathrm{n}\right)$, and chech whether it satisfies the time invariance property or not.
5. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} \mathrm{pi}^{*} 2^{*} n\right)$, and chech whether it satisfies the time invariance property or not
6. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.3^{*} \mathrm{n}\right)$, and chech whether it satisfies the time invariance property or not.
7. Write a MATLAB program to verify the time variance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi} i^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi} i^{*} 0.3^{*} \mathrm{n}\right)$, and chech whether it satisfies the time invariance property or not.
8. Write a MATLAB program to verify the non linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}^{*} 0.3^{*} \mathrm{n}\right)$, and chech whether it satisfies the linearity property or not
9. Write a MATLAB program to verify the time variance prpoerty of the following sequency $x 1=\sin \left(2^{*} p i^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} p i^{*} 2^{*} n\right)$, and check whether it satisfies the time invariance property or not.

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10. Write a MATLAB program to verify the non linearity prpoerty of the following sequency $x 1=\sin \left(2^{*}\right.$ pi$\left.^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*}\right.$ pi$\left.^{*} 2^{*} n\right)$, and check whether it satisfies the linearity property or not.
11. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}^{*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not.
12. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
13. Write a MATLAB program to verify the linearity prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
14. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*}\right.$ pi*$\left.^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*}\right.$ pi*$\left.^{*} 2^{*} n\right)$, and check whether it satisfies the time invariance property or not.
15. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*}\right.$ pi$\left.^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*}\right.$ pi$\left.^{*} 2^{*} n\right)$, and check whether it satisfies the time invariance property or not
16. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.
17. Write a MATLAB program to verify the time variance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.
18. Write a MATLAB program to verify the non linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}{ }^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
19. Write a MATLAB program to verify the time variance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{p} \mathrm{i}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{p} \mathrm{i}^{*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.
20. Write a MATLAB program to verify the non linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}^{*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not.
21. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}{ }^{*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not.
22. Write a MATLAB program to verify the linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
23. Write a MATLAB program to verify the linearity prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
24. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*} p i^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} p i^{*} 2^{*} n\right)$, and check whether it satisfies the time invariance property or not.
25. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} \mathrm{p} i^{*} 2^{*} n\right)$, and check whether it satisfies the time invariance property or not.
26. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi}^{*} 1^{*} n\right) ; x 2=\sin \left(2^{*} \mathrm{pi}^{*} 12^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not
27. Write a MATLAB program to verify the time invariance prpoerty of the following sequency $\mathrm{x} 1=\sin \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right) ; 2^{*} \cos \left(2^{*} \mathrm{pi}{ }^{*} 0.5^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.
28. Write a MATLAB program to verify the time variance prpoerty of the following sequency $\mathrm{x} 1=\cos \left(2^{*} \mathrm{pi}^{*} 0.1^{*} \mathrm{n}\right) ; \cos \left(2^{*} \mathrm{pi}^{*} 0.4^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.
29. Write a MATLAB program to verify the non linearity prpoerty of the following sequency $x 1=\sin \left(2^{*} \mathrm{pi} 0.1^{*} \mathrm{n}\right) ; \sin \left(2^{*} \mathrm{pi}^{*} 0.3^{*} \mathrm{n}\right)$, and check whether it satisfies the linearity property or not
30. Write a MATLAB program to verify the time variance prpoerty of the following sequency $\mathrm{x} 1=6^{*} \sin \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{n}\right) ; \mathrm{x} 2=\sin \left(2^{*} \mathrm{pi}{ }^{*} 2^{*} \mathrm{n}\right)$, and check whether it satisfies the time invariance property or not.

## Real Time Applications:

- Wave Propagation such as sound and electromagnetic waves.
- Electrical circuits composed of resistors, capacitors and inductors.
- Robotics Applications.

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EXPERMENT NO:8

## Computation of unit sample, unit step and sinusoidal response of the given LTI system and verifying its physical reliability and stability Properties.

## AIM: -

To Unit Step and Sinusoidal Response of The Given LTI System And Verifying Its Physical Reliability And Stability Properties.

## SOFTWARE REQURIED: -

## 1.MATLAB R2010a.

2.Windows XP SP2.

## THEORY: -

A discrete time system performs an operation on an input signal based on predefined criteria to produce a modified output signal. The input signal $x(n)$ is the system excitation, and $y(n)$ is the system response. The transform operation is shown as,
If the input to the system is unit impulse i.e. $\mathrm{x}(\mathrm{n})=\delta(\mathrm{n})$ then the output of the

system isknown as impulse response denoted by $h(n)$ where,

$$
\mathrm{h}(\mathrm{n})=\mathrm{T}[\delta(\mathrm{n})]
$$

we know that any arbitrary sequence $x(n)$ can be represented as a weighted sum ofdiscrete impulses. Now the system response is given by,

$$
\mathrm{y}(\mathrm{n})=\mathrm{T}[\mathrm{x}(\mathrm{n})]=\mathrm{T}\left[\sum_{\mathrm{v}=\mathrm{m}}^{\infty} \mathrm{x}(\mathrm{k}) \delta(\mathrm{n}-\mathrm{k})\right]
$$

For linear system (1) reduces to

$$
\mathrm{y}(\mathrm{n})=\sum_{\mathrm{k}=-\infty}^{\infty} \mathrm{x}(\mathrm{k}) \mathrm{T}[\delta(\mathrm{n}-\mathrm{k})]
$$

$$
\mathbf{H}(\mathbf{z})=\frac{\mathbf{b}_{0}+\mathbf{b}_{1} Z^{-1}+\mathbf{b}_{2} Z^{-2}+\ldots \ldots \ldots \ldots . \mathbf{b}_{\mathrm{N}, 1} Z^{(N-1)}+\mathbf{b}_{N} Z^{-N}}{\mathbf{1}+\mathbf{a}_{1} Z^{-1}+\mathbf{a}_{2} Z^{-2}+\ldots \ldots \ldots \ldots \mathbf{a}_{N+1} Z^{(N-1)}+\mathbf{a}_{N} Z^{-N}} \quad \mathbf{H}(Z)=\frac{\sum_{\mathbf{k}=0}^{M} \mathbf{b}_{\mathbf{k}} X(\mathbf{n}-\mathbf{k})}{\sum_{\mathbf{k}=1}^{N} \mathbf{a}_{\mathbf{k}} X(\mathbf{n}-\mathbf{k})}
$$

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## PROCEDURE: -

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program

PROGRAM: -
\%calculate and plot the impulse response and step response\% clc; clear all;
close all;
$\mathrm{b}=[1]$;
$a=[1,-1, .9]$;
$\mathrm{x}=\mathrm{impseq}(0,-20,120)$;
$\mathrm{n}=[-20: 120] ;$
$\mathrm{h}=$ filter $(\mathrm{b}, \mathrm{a}, \mathrm{x})$;
subplot( $3,1,1$ );
stem(n,h);
title('impulse response');
xlabel('n');
ylabel('h(n)');
$=$ stepseq(0,-20,120);
$\mathrm{s}=$ filter $(\mathrm{b}, \mathrm{a}, \mathrm{x})$;
$s=$ filter $(b, a, x)$;
subplot(3,1,2);
stem(n,s);
title('step response');
xlabel('n');
ylabel('s(n)');
$\mathrm{t}=0: 0.1: 2^{*} \mathrm{pi}$;
$\mathrm{x} 1=\sin (\mathrm{t})$;
\%impseq(0,-20,120);
$\mathrm{n}=[-20: 120]$;
$\mathrm{h}=$ filter $(\mathrm{b}, \mathrm{a}, \mathrm{x} 1)$;
subplot(3,1,3);stem(h);
title('sin response');
xlabel('n');
ylabel('h(n)'); figure;
zplane(b,a);


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Impulse response of a system $h(t)$ is $\exp (-2 * t) * \sinh (t)$. The step response of a system is $1 / 6^{*} \exp \left(-3^{*} t\right)-1 / 2 * \exp (-t)+1 / 3$.

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## RESULT: -

In this experiment computation of unit sample, unit step and sinusoidal response of the given LTI system and verifying its physical Reliability and Stability Properties using MATLAB.

## VIVA QUESTIONS: -

1.What operations can be performed on signals and sequence?
2.Define causality?
3.Define scaling property and give its importance?
4.Define shifting property and give its importance?
5.Define folding property and give its importance?
6.Define stability?
7.Give the importance of Causality?
8.Give the importance of Stability?
9. Define Impulse Response?
10.Define Step Response?

## EXERCISE PROGRAM: -

1. Write a MATLAB program for generating $u(n)-u(n-1)$.
2. Write a MATLAB program for generating delayed unit step response
3. Write a MATLAB program for generating delayed impulse response
4. Write a MATLAB program for generating $u(n)+u(n-1)$ and verify how matlab reacts to it.
5. write a MATLAB program to find the energy \& power of the signal $x(t)=10 \sin (10 t)$.
6. write a MATLAB program to find the even \& odd of the signal $x(t)=e^{\wedge} 2 t$.
7. write a MATLAB program to find the even \& odd of the signal $x(t)=\sin (t)$.
8. write a MATLAB program to find the even \& odd of the signal $x(t)=\cos (t)$.
9. write a MATLAB program to find the energy \& power of the signal $x(t)=\sin (t)$.
10. write a MATLAB program to find the energy \& power of the signal $x(t)=e^{\wedge} 2 t$.
11. Write a MATLAB program for generating $u(n-2)-u(n-1)$.
12. Write a MATLAB program for generating delayed step response with magnitude 2
13. Write a MATLAB program for generating delayed impulse response with magnitude 2.
14. Write a MATLAB program for generating $u(n+1)+u(n-1)$ and verify how matlab reacts to it.
15. Write a MATLAB program to find the energy \& power of the signal $x(t)=20 \sin (5 t)$.
16. Write a MATLAB program to find the even \& odd of the signal $x(t)=e^{\wedge} 3 t$.
17. Write a MATLAB program to find the even \& odd of the signal $x(t)=\sin (t)+\cos (t)$.
18. Write a MATLAB program to find the even \& odd of the signal $x(t)=\cos (t)-\sin (t)$.
19. Write a MATLAB program to find the energy \& power of the $\operatorname{signal} x(t)=\sin (t)-\cos (t)$.
20. Write a MATLAB program to find the energy \& power of the signal $x(t)=e^{\wedge} 4 t$.
21. Write a MATLAB program for generating $u(n+2)-u(n-1)$.
22. Write a MATLAB program for generating delayed unit step response
23. Write a MATLAB program for generating delayed impulse response
24. Write a MATLAB program for generating $u(n-3)+u(n-1)$ and verify how matlab reacts to it.
25. Write a MATLAB program to find the energy \& power of the signal $x(t)=5 \sin (20 t)$.
26. Write a MATLAB program to find the energy \& power of the signal $x(t)=30 \sin (5 t)$.
27. Write a MATLAB program to find the even \& odd of the signal $x(t)=e^{\wedge} 4 t$.
28. Write a MATLAB program to find the even \& odd of the signal $x(t)=\sin (t)-\cos (t)$.
29. Write a MATLAB program to find the even \& odd of the signal $x(t)=\cos (t)-2 \sin (t)$.
30. Write a MATLAB program to find the energy \& power of the $\operatorname{signal} x(t)=\sin (t)-3 \cos (t)$.

## Real Time Applications:

- Electronic Circuits such as amplifiers and filters.
- Mechanical motion from the interaction of masses, springs and dashpots (dampers).
- LTI systems


## Basic Simulation Lab Manual <br> EXPERMENT NO:9 <br> Demonstration of Gibbs Phenomenon

## AIM: -

To demonstrate Gibbs Phenomenon using MATLAB.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

THEORY: -

## Gibbs Phenomenon:

The peculiar manner in which the Fourier series of a piecewise continuously differentiable periodic function behaves at a jump discontinuity: the nth partial sum of the Fourier series has large oscillations near the jump, which might increase the maximum of the partial sum above that of the function itself. The overshoot does not die out as the frequency increases, but approaches a finite limit. The Gibbs phenomenon involves both the fact that Fourier sums overshoot at a jump discontinuity, and that this overshoot does not die out as the frequency increases.
The best known version of the Gibbs phenomenon is the overshoot that arises when a discontinuous function is represented by a truncated set of Fourier expansion terms. The situation is similar if the truncated Fourier expansion is instead obtained by means of interpolation on an equi spaced grid.

## PROCEDURE: -

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window

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## PROGRAM: -

\%Gibbs phenomenon\%
clc;
clear all;
close all; t=0:0.01:1;
$\mathrm{N}=$ input('enter no of harmonics');
$\mathrm{x}=$ square $\left(2^{*} \mathrm{pi}^{*} \mathrm{t}\right)$;
plot( $\mathrm{t}, \mathrm{x}$ );
hold on;
$\mathrm{gp}=0$;
for $\quad n=1: 2: N$;
$\mathrm{gp}=\mathrm{gp}+(4 /(\mathrm{n} * \mathrm{pi}))^{*} \sin \left(2^{*} \mathrm{pi}^{*} \mathrm{n}^{*} \mathrm{t}\right)$;
end; $\operatorname{plot}(\mathrm{t}, \mathrm{gp})$; hold off;
xlabel('time');
ylabel('amplitude');
title('gibbs phenomenon');

## OUTPUT: -

Gibbs phenomenon
enter no of harmonics 5


```
```

PROGRAM: -

```
```

PROGRAM: -
clc; clear all;
clc; clear all;
close all;
close all;
N=input('enter the no. of signals to reconstruct=')
N=input('enter the no. of signals to reconstruct=')
n_har=input('enter the no. of harmonics in each
n_har=input('enter the no. of harmonics in each
signal=');
signal=');
t=-1:0.001:1;
t=-1:0.001:1;
omega_0=2*pi;
omega_0=2*pi;
for k=1:N
for k=1:N
x=0.5;
x=0.5;
for n=1:2:n_har(k) b_n=2/(n*pi);
for n=1:2:n_har(k) b_n=2/(n*pi);
x=x+b_n*sin(n*omega_0*t);
x=x+b_n*sin(n*omega_0*t);
end subplot(N,1,k);
end subplot(N,1,k);
plot(t,x); xlabel('time--->');
plot(t,x); xlabel('time--->');
ylabel('amp>');
ylabel('amp>');
axis([-1 1-0.5 1.5]);
axis([-1 1-0.5 1.5]);
text(0.55,1.0,['no.of har=',num2str(n_har(k))]);
text(0.55,1.0,['no.of har=',num2str(n_har(k))]);
end

```
```

end

```
```


enter the no. of signals to reconstruct=3 enter the no. of harmonics in each signal $=[3,5,59]$

## RESULT: -

In this experiment Gibbs phenomenon have been demonstratedUsing MATLAB.

## EXERCISE PROGRAM: -

1.Write the MATLAB program to perform convolution between the following sequencesX(n)=[lllll 18973$], h(n)=\left[\begin{array}{lll}2 & 4 & 5\end{array}\right]$.
2. Write a mat lab program to perform the convolution between sinusoidal and ramp function andsee how mat lab reacts to it.
3. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
4. Write a MATLAB program to perform convolution between sinusoidal and ramp signal andsee how mat lab reacts to it.
5. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}8 & 5 & 6\end{array}\right]$ and $y$ ( n ) $=[-1-2]$ and see how matlab reacts to it.
6. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & -3 & 4\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{lll}1 & 2 & 3\end{array} 4\right]$ and see how matlab reacts to it.
7. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 0 & 1\end{array} 1\right]$ and $y$ (n) =[ $\left.\begin{array}{llll}1 & 0 & 0 & 0\end{array} 0\right]$ and see how matlab reacts to it.
8. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{llll}1 & 1 & 1 & 0\end{array} 0000\right.$ and $y(n)=\left[\begin{array}{llllll}1 & 0 & 1 & 0 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
9.Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array} 0\right]$ and $y$ ( n ) $=\left[\begin{array}{llll}1 & 1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.

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10. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}6 & 9 & 5\end{array}\right.$ 2] and $y(n)$ = [85642] and see how matlab reacts to it.
11. Write the MATLAB program to perform convolution between the following sequencesX(n)=[24 493 3], $h(n)=\left[\begin{array}{lll}1 & 3 & 7\end{array}\right]$.
12. Write a mat lab program to perform the convolution between step and ramp function and seehow mat lab reacts to it.
13. Write a MATLAB program to perform convolution between sinusoidal and step signal andsee how mat lab reacts to it.
14. Write a MATLAB program to perform convolution between impulse and ramp signal and seehow mat lab reacts to it.
15. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}3 & 2 & 6\end{array}\right]$ and $y$ (n) $=[-2-4]$ and see how matlab reacts to it.
16. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & -4 & 2\end{array}\right]$ and $y(n)$ = [4 2334 4] and see how matlab reacts to it.
17. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 1 & 0\end{array} 1\right]$ and $y$ ( $n$ ) $=\left[\begin{array}{lll}1 & 0 & 1\end{array} 1\right]$ and see how matlab reacts to it.
18. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 1 & 2 \\ 2 & 1 & 0\end{array}\right]$ andy $(\mathrm{n})=\left[\begin{array}{llllll}2 & 0 & 1 & 1 & 0 & 0\end{array} 20\right.$ 0nd see how matlab reacts to it.
19. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 2 & 0\end{array}\right]$ and $y$ ( n ) $=\left[\begin{array}{llll}1 & 1 & 2 & 2\end{array}\right]$ and see how matlab reacts to it.
20. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 1 & 4 \\ 5 & 3\end{array}\right]$ and $y(n)$ = [2 16621$]$ and see how matlab reacts to it.
21. Write the MATLAB program to perform convolution between the following sequencesX(n)=[llllll $\left.\begin{array}{lll}8 & 7 & 3\end{array}\right], h(n)=\left[\begin{array}{lll}1 & 4 & 2\end{array}\right]$.
22. Write a mat lab program to perform the convolution between sinusoidal and ramp functionand see how mat lab reacts to it.
23. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
24. Write a MATLAB program to perform convolution between sinusoidal and ramp signal andsee how mat lab reacts to it.
25. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}4 & 5 & 2\end{array}\right]$ and $y$ (n) $=[-2-1]$ and see how matlab reacts to it.
26. Write a MATLAB program to perform the correlation between $X(n)=\left[\begin{array}{llll}1111 & 1 & 0 & 0\end{array}\right]$ and $y(n)=\left[\begin{array}{llllll}1 & 0 & 1 & 0 & 1 & 0\end{array} 10\right.$ 0 and see how matlab reacts to it.
27. Write a MATLAB program to perform the correlation between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array} 0\right]$ and $y$ ( n ) $=\left[\begin{array}{llll}1 & 1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.
28. Write a MATLAB program to perform the correlation between $X(n)=\left[\begin{array}{ll}6 & 9 \\ 7 & 2\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{llll}5 & 6 & 4 & 2\end{array}\right]$ and see how matlab reacts to it.
29. Write the MATLAB program to perform correlation between the following sequencesX(n)=[24 493 3], $h(n)=\left[\begin{array}{lll}1 & 3 & 7\end{array}\right]$.

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30. Write a mat lab program to perform the correlation between step and ramp function and seehow mat lab reacts to it.

## VIVA QUESTIONS: -

1. Define Gibb's Phenomenon?
2. What is the importance of Gibb's Phenomenon?
3. What is Static and Dynamic System?
4. What is Causal Signal?
5. What is Causality Condition of the Signal?
6. Define Noise?
7. What is the importance of FS?
8. What is the importance of FT?
9. Define LTV system?
10.Define LTI system?

## Real Time Applications:

- The Gibbs phenomenon, discovered by Henry Wilbraham and rediscovered by J. Willard Gibbs (1899), is the peculiar manner in which the Fourier series ofa piecewise continuously differentiable periodic function behaves at a jump discontinuity.
- To Eliminate noise in Filters.


## Finding the Fourier transform of a given signal and plot its magnitude and phase spectrum

AIM: -
To obtain Fourier Transform and Inverse Fourier Transform of a givensignal / sequence and to plot its Magnitude and Phase Spectra.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

THEORY:-
Fourier Transform Theorems:
We may use Fourier series to motivate the Fourier transform as follows. Suppose that $f$ is a function which is zero outside of some interval $[-L / 2, \mathrm{~L} / 2]$. Then for any $\mathrm{T} \geq \mathrm{L}$ we mayexpand $f$ in a Fourier series on the interval [-T/2,T/2], where the "amount" of the wave e2minx/T in the Fourier series of $f$ is given by

By definition
Fourier Transform of $x(t): \mathcal{F}[x(t)]$ or $X(w)$ :

$$
X(\omega)=\int_{-\infty}^{\infty} x(t) e^{-j \omega t} d t
$$

Inverse Fourier Transform of $X(w): \mathcal{F}^{-1}[X(w)]$ :

$$
x(t)=\frac{1}{2 \pi} \int_{-\infty}^{\infty} X(\omega) e^{j \omega t} d \omega
$$

## Basic Simulation Lab Manual

The fast Fourier transform (FFT) is an efficient algorithm for computing the DFT of a sequence; it is not a separate transform. It is particularly useful in areas such as signal and image processing, where its uses range from filtering, convolution, and frequency analysis to power spectrum estimation
For length N input vector x , the DFT is a length N vector X , with elements N

$$
\mathrm{X}(\mathrm{k})=\operatorname{sum} \mathrm{x}(\mathrm{n})^{*} \exp \left(-\mathrm{j}^{*} 2^{*} \mathrm{pi}^{*}(\mathrm{k}-1) *(\mathrm{n}-1) / \mathrm{N}\right), 1<=\mathrm{k}<=\mathrm{N} . \mathrm{n}=1
$$

The inverse DFT (computed by IFFT) is given by N

$$
x(n)=(1 / N) \operatorname{sum} X(k)^{*} \exp \left(j^{*} 2^{*} \mathrm{pi}^{*}(k-1)^{*}(n-1) / N\right), 1<=n<=N . k=1
$$

## PROCEDURE: -

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## Basic Simulation Lab Manual

PROGRAM: -

```
%Fourier Transform%
clc;
clear all;
close all;
syms t;
x=exp(-2*t)*heaviside(t);
y=fourier(x);
disp('Fourier Transform of input signal'); y
z=ifourier(y);
disp('Inverse Fourier Transform of input signal'); z
mg=abs(y);
subplot(2,1,1);
ezplot(mg); xlabel('time'); ylabel('amplitude');
title('magnitude spectrum of a input signal'); grid;
pha=atan(imag(y)/real(y)); subplot(2,1,2); ezplot(pha);
xlabel('time'); ylabel('amplitude');
title('phasespectrum of a input signal'); grid;
OUTPUT:-
Fourier Transform
Fourier Transform of input signal Y=
1/(2+w*i)
Inverse Fourier Transform of input signal Z=
Heaviside(x)/exp(2*x)
```

Basic Simulation Lab Manual

| PROGRAM:- | To find inverse Fourier transforms of Given functions. |
| :---: | :---: |
| To find Fourier transform | $\mathrm{F} 1=\mathrm{A}^{*} \mathrm{pi}^{*}(\operatorname{dirac}(\mathrm{w}-\mathrm{o})+\operatorname{dirac}(\mathrm{w}+\mathrm{o})$ ); |
| clc; clear all; close all; syms ts; | f1=ifourier (F1,t); |
| syms w real; | disp('the inverse fourier transform of ............. |
| syms A real; | .................... ${ }^{*} \mathrm{p}^{*}{ }^{*}(\operatorname{dirac}(\mathrm{w}-\mathrm{o})+\operatorname{dirac}(\mathrm{w}+\mathrm{o})=$ '); |
| syms o real; | disp(f1); |
| syms b float; | $\mathrm{F} 2=\mathrm{A}^{*} \mathrm{pi}^{*}(\operatorname{dirac}(\mathrm{w}-\mathrm{o})-\operatorname{dirac}(\mathrm{w}+\mathrm{o})$ )/i; |
| $\mathrm{f}=\operatorname{dirac}(\mathrm{t})$; | f2=ifourier(F2,t); |
| $\mathrm{F}=$ fourier(f); | disp('the inverse fourier transform of............... |
| disp('the fourier transform of dirac ( t ) = '); | ................ ${ }^{*} \mathrm{pi}^{*}(\operatorname{dirac}(\mathrm{w}-\mathrm{o})+\operatorname{dirac}(\mathrm{w}+\mathrm{o}) / \mathrm{i}=$ ' $)$; |
| disp(F); | disp(f2); |
| f1=A*heaviside(t); F1=fourier(f1); | $\mathrm{F} 3=\mathrm{A} /\left(1+\mathrm{i}^{*} \mathrm{w}\right)$; f3=ifourier(F3,t); |
| disp('the fourier transform of $\mathrm{A}=$ '); disp(F1); | disp('the inverse fourier transform of $A /(1+j w)=$ '); |
| f2 = ${ }^{*} \exp (-\mathrm{t}) *$ heaviside( t ); $\mathrm{F} 2=$ fourier(f2); | disp(f3); |
| disp('the fourier transform of $\exp (-\mathrm{t})=$ ' $)$; | $\mathrm{F} 4=\left(3^{*} \mathrm{i}^{*} \mathrm{w}+14\right) /\left(\left(i^{*} \mathrm{w}\right)^{\wedge} 2+7^{*} \mathrm{i}^{*} \mathrm{w}+12\right)$; f4=ifourier (F4,t); |
| disp(F2); | disp('the inverse fourier transform of.......... |
| $\mathrm{f} 3=\mathrm{A}^{*} \mathrm{t}^{*} \exp \left(-\mathrm{b}^{*} \mathrm{t}\right)^{*}$ heaviside( t$)$; F3=fourier(f3); | .............(3*i*w+14)/((i*w)^2+7*i*w+12)='); |
| disp('the fourier transform of $\mathrm{A}^{*} \mathrm{t}^{*} \exp \left(-\mathrm{b}^{*} \mathrm{t}\right)^{*} \mathrm{u}(\mathrm{t})$ | disp(f4); |
| ='); disp(F3); |  |
| $\mathrm{f} 4=\sin \left(\mathrm{O}^{*} \mathrm{t}\right)$; |  |
| F4=fourier(f4); |  |
| disp('the fourier transform of $\sin \left(\mathrm{o}^{*} \mathrm{t}\right)=$ '); |  |
| disp(F4); |  |

## OUTPUT:-

the fourier transform of $\operatorname{dirac}(\mathrm{t})=1$
the fourier transform of $\mathrm{A}=\mathrm{A}^{*}\left(\mathrm{pi}^{*} \operatorname{dirac}(\mathrm{w})-\mathrm{i} / \mathrm{w}\right)$ the fourier transform of $\exp (-\mathrm{t})=\mathrm{A} /\left(1+\mathrm{i}^{*} \mathrm{w}\right)$
the fourier transform of $A * t * \exp \left(-b^{*} t\right) * u(t)=A /\left(b+i^{*} w\right)^{\wedge} 2$
the fourier transform of $\sin \left(\mathrm{o}^{*} \mathrm{t}\right)=* \mathrm{pi}^{*}(\operatorname{dirac}(\mathrm{w}+\mathrm{o})-\operatorname{dirac}(\mathrm{w}-\mathrm{o}))$
the inverse fourier transform of $\mathrm{A}^{*} \mathrm{pi}^{*}\left(\operatorname{dirac}(\mathrm{w}-\mathrm{o})+\operatorname{dirac}(\mathrm{w}+\mathrm{o})=\mathrm{A} * \cos \left(\mathrm{o}^{*} \mathrm{t}\right)\right.$
the inverse fourier transform of $\mathrm{A}^{*} \mathrm{pi}^{*}\left(\operatorname{dirac}(\mathrm{w}-\mathrm{o})+\operatorname{dirac}(\mathrm{w}+\mathrm{o}) / \mathrm{i}=\mathrm{A}^{*} \sin \left(\mathrm{o}^{*} \mathrm{t}\right)\right.$
the inverse fourier transform of $\mathrm{A} /(1+\mathrm{jw})=\mathrm{A} * \exp (-\mathrm{t}) *$ heaviside $(\mathrm{t})$
the inverse fourier transform of $\left(3 * i^{*} \mathrm{w}+14\right) /\left(\left(\mathrm{i}^{*} \mathrm{w}\right)^{\wedge} 2+7 * \mathrm{i}^{*} \mathrm{w}+12\right)=$ heaviside $(\mathrm{t})^{*}(-2 * \exp (-4 * \mathrm{t})+5 * \exp (-3 * \mathrm{t}))$

Basic Simulation Lab Manual


RESULT: -
In this experiment the Fourier transform of a given signal and plotting its magnitude and phase spectrum have been demonstrated using MATLAB.

Magnitude and Phase Spectrum of Fourier Transform

## PROGRAM:-

clc; clear all; close all; syms ts ;
syms w float;
$\mathrm{f}=3^{*} \exp (-\mathrm{t}) *$ heaviside $(\mathrm{t})$;
$\mathrm{F}=$ fourier(f);
disp('the fourier transform of $\qquad$
...........3*exp(-t)*u(t) =');
$\operatorname{disp}(\mathrm{F})$;
$\mathrm{w}=-2^{*}$ pi:pi/50:2*pi;
F1=subs(F,w);
Fmag=abs(F1); \% to find magnitude Fphas=angle(F1);\% to find phase subplot(2,1,1);
plot(w,Fmag); xlabel('w>');
ylabel('Magnitude>');
title('Magnitude spectrum'); grid;
subplot(2,1,2); $\quad \operatorname{plot}(w, F p h a s)$;
xlabel('w>');
ylabel('Phase in radians>');
title('Phase spectrum'); grid;

## VIVA QUESTIONS: -

1.Define Fourier Series?
2. What are the properties of Continuous-Time Fourier Series?
3. What is the Sufficient condition for the existence of F.T?
4. Define the F.T of a signal?
5.What is the difference b/w F.T\&F.S?
6.Define Scaling Property of FT?
7. Explain Time Convolution Property of FT?
8. Explain Frequency Convolution Property of FT?
9. Explain the linearity property?
10. Describe the advantages of FT?

## EXERCISE PROGRAMS

1. Write a MATLAB program to find the cross correlation using FFT.
2. Write a MATLAB program to find F.T of the causal signal $x(t)=t$
3. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge}-a t$
4. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge}$ at
5. Write a MATLAB program to find F.T of the causal signal $x(t)=t{ }^{\wedge}$ at
6. Write a MATLAB program to find F.T of the causal signal $x(t)=t e^{\wedge}-a t$
7. Write a MATLAB program to find F.T of the causal signal $x(t)=$ cost
8. Write a MATLAB program to find F.T of the causal signal $x(t)=\sin t$
9. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge} \operatorname{atcos}(t)$
10.Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge} \operatorname{atsin}(t)$
10. Write a MATLAB program to find the cross correlation using DFT.
11. Write a MATLAB program to find F.T of the causal signal $x(t)=a t$
12. Write a MATLAB program to find F.T of the causal signal $x(t)=10 e^{\wedge}$-at
13. Write a MATLAB program to find F.T of the signal $x(t)=1$
14. Write a MATLAB program to find F.T of the causal signal $x(t)=$ impulse function
15. Write a MATLAB program to find F.T of the causal signal $x(t)=$ Delta function
16. Write a MATLAB program to find F.T of the causal signal $x(t)=\cos (a t)$
17. Write a MATLAB program to find F.T of the causal signal $x(t)=\sin (a t)$
18. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge} \operatorname{atcos}(a t)$
19. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge}$ atsin(at)
20. Write a MATLAB program to find the auto correlation using FFT.
21. Write a MATLAB program to find F.T of the causal signal $x(t)=5 t$
22. Write a MATLAB program to find F.T of the causal signal $x(t)=5 e^{\wedge}-a t$
23. Write a MATLAB program to find F.T of the causal signal $x(t)=5 e^{\wedge}$ at
24. Write a MATLAB program to find F.T of the causal signal $x(t)=5 t e^{\wedge}$ at
25. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge}-2 t$
26. Write a MATLAB program to find F.T of the causal signal $x(t)=e^{\wedge} 5 t$

Basic Simulation Lab Manual
28. Write a MATLAB program to find F.T of the causal signal $x(t)=t e^{\wedge} 4 t$
29. Write a MATLAB program to find F.T of the causal signal $x(t)=t e^{\wedge}-4 t$
30. Write a MATLAB program to find F.T of the causal signal $x(t)=4 \operatorname{cost}$

## Real Time Applications:

Fourier transforms having following applications
$>$ Analysis of differential equations
$>$ Fourier transform spectroscopy
$>$ Quantum mechanics
$>$ Signal processing applications etc

Basic Simulation Lab Manual
EXPERMENT NO:11

## Waveform Synthesis using Laplace Transform

AIM: -
To perform waveform synthesis using Laplace Transforms of a given signal

## SOFTWARE REQURIED: -1.

MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

## Bilateral Laplace transform:

When one says "the Laplace transform" without qualification, the unilateral or one-sided transform is normally intended. The Laplace transform can be alternatively defined as the bilateral Laplace transform or two-sided Laplace transform by extending the limits of integration to be the entire real axis. If that is done the common unilateral transform, simply becomes a special case of the bilateral transform where the definition of the function being transformed is multiplied by the Heaviside step function.

$$
\begin{aligned}
\mathcal{L}\{f(t)\} & =\int_{0^{-}}^{\infty} e^{-s t} f(t) d t \\
& =\left[\frac{f(t) e^{-s t}}{-s}\right]_{0^{-}}^{\infty}-\int_{0^{-}}^{\infty} \frac{e^{-s t}}{-s} f^{\prime}(t) d t \quad \text { (by parts) } \\
& =\left[-\frac{f\left(0^{+}\right)}{-s}\right]+\frac{1}{s} \mathcal{L}\left\{f^{\prime}(t)\right\},
\end{aligned}
$$

## Inverse Laplace transform

The inverse Laplace transform is given by the following complex integral, which is known by various names (the Bromwich integral, the Fourier-Mellin integral, and Mellin's inverse formula):

$$
f(t)=\frac{1}{2 \pi j} \int_{\alpha-j \infty}^{\alpha+j \infty} F(s) e^{s t} d s
$$

## Example:

Let $\mathrm{y}(\mathrm{t})=\mathrm{u}(\mathrm{t})$. We have

$$
\begin{aligned}
u(t) & =1 \quad \text { for } t \geq 0 \\
& =0 \quad \text { for } t<0 \\
\mathbf{L}\{u(t)\} & =\int_{0}^{\infty} u(t) \cdot e^{-s t} d t=\int_{0}^{\infty} 1 \cdot e^{-s t} d t=\left[\frac{e^{-s t}}{-s}\right]_{0}^{\infty} \\
& =\left[\frac{e^{-\infty}}{-s}-\frac{e^{0}}{-s}\right] \quad \text { as } e^{-\infty}=0 \\
L\{u(t)\} & =\frac{1}{s}
\end{aligned}
$$

The integral converges if $s>1$. The functions $\exp (t)$ and $1 /(s-1)$ are partner functions.

Basic Simulation Lab Manual

## PROCEDURE: -

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

```
%Laplace Transform%
clc
clear all;close all;syms t;
x=exp(-2*t)*heaviside(t);y=laplace(x);
disp('Laplace Transform of input
signal');y
z=ilaplace(y);
disp('Inverse Laplace Transform of input signal');z
```


## OUTPUT: -

## Laplace Transform

Laplace Transform of input
signal $Y=$
$1 /(\mathrm{s}+2)$
Inverse Laplace Transform of input
signalZ=
$1 / \exp \left(2^{*} \mathrm{t}\right)$

## RESULT: -

Laplace and inverse laplace transforms were verified using MATLAB functions.

## VIVA QUESTIONS: -

1.Define Laplace-Transform?
2. What is the Condition for Convergence of the L.T?
3. What is the Region of Convergence(ROC)?
4. State the Shifting property of L.T?
5. State convolution Property of L.T?6.Define Scaling Property of L.T?
7. Explain Time Convolution Property of L.T?
8. Explain Frequency Convolution Property of L.T?
9. Explain the linearity property of L.T?10.Describe the advantages of L.T?

## EXERCISE PROGRAMS

1. Write a MATLAB program to find L.T of the causal signal $x(t)=t^{\wedge} 2$
2. Write a MATLAB program to find L.T of the causal signal $x(t)=t$
3. Write a MATLAB program to find L.T of the causal signal $x(t)=e^{\wedge}-a t$
4. Write a MATLAB program to find L.T of the causal signal $x(t)=e^{\wedge}$ at
5. Write a MATLAB program to find L.T of the causal signal $x(t)=t{ }^{\wedge}$ at
6. Write a MATLAB program to find L.T of the causal signal $x(t)=t e^{\wedge}-a t$
7. Write a MATLAB program to find L.T of the causal signal $x(t)=$ cost
8. Write a MATLAB program to find L.T of the causal signal $x(t)=\operatorname{sint}$
9. Write a MATLAB program to find L.T of the causal signal $x(t)=e^{\wedge}$ atcost
10. Write a MATLAB program to find L.T of the causal signalv $x(t)=$ $\mathrm{e}^{\wedge}$ atsint.11.Write a MATLAB program to find the cross correlation using DFT.
11. Write a MATLAB program to find L.T of the causal signal $x(t)=a t$
12. Write a MATLAB program to find L.T of the causal signal $x(t)=10 e^{\wedge}$-at
13. Write a MATLAB program to find L.T of the signal $x(t)=1$
14. Write a MATLAB program to find L.T of the causal signal $x(t)=$ impulse function
15. Write a MATLAB program to find L.T of the causal signal $x(t)=$ Delta function
16. Write a MATLAB program to find L.T of the causal signal $x(t)=\cos (a t)$
17. Write a MATLAB program to find L.T of the causal signal $x(t)=\sin (a t)$
18. Write a MATLAB program to find L.T of the causal signal $x(t)=e^{\wedge} \operatorname{atcos}(a t)$
19. Write a MATLAB program to find L.T of the causal signal $x(t)=e^{\wedge}$ atsin $(a t)$
20. .Write a MATLAB program to find the auto correlation using L.T.
21. Write a MATLAB program to find L.T of the causal signal $x(t)=5 t$
22. Write a MATLAB program to find L.T of the causal signal $x(t)=5 e^{\wedge}-a t$
23. Write a MATLAB program to find L.T of the causal signal $x(t)=5 e^{\wedge}$ at
24. Write a MATLAB program to find L.T of the causal signal
$\mathrm{x}(\mathrm{t})=5$ te^at26.Write a MATLAB program to find L.T of the causal
signal $\mathrm{x}(\mathrm{t})=\mathrm{e}^{\wedge} 4 \mathrm{t}$
25. Write a MATLAB program to find L.T of the causal signal $x(t)=t e^{\wedge} 5 t$
26. Write a MATLAB program to find L.T of the causal signal $x(t)=t e^{\wedge}-4 t$
27. Write a MATLAB program to find L.T of the causal signal $x(t)=7$ cost
28. Write a MATLAB program to find L.T of the causal signal $x(t)=5 \sin t$

## Real Time Applications:

Laplace transforms having following
$\square \quad$ applicationsAnalysis of differential
$\square \quad$ equations
$\square \quad$ Laplace transform
$\square \quad$ spectroscopyQuantum
mechanics
Signal processing applications etc

## EXPERMENT NO:12

## GAUSSIAN NOISE

## AIM: -

To Generate Gaussian Noise and to Compute its Mean, M.S. Values, Skew, kurtosis,PS and PDF.

## SOFTWARE REQURIED: -

## 1.MATLAB R2010a.

2.Windows XP SP2.

## THEORY:-

Gaussian noise is statistical noise that has a probability density function (abbreviatedpdf) of the normal distribution (also known as Gaussian distribution). In other words, the values tha the noise can take on are Gaussian-distributed. It is most commonly used as additive white noise to yield additive white Gaussian noise (AWGN).Gaussian noise is properly defined as the noise with a Gaussian amplitude distribution.says nothing of the correlation of the noise in timeor of the spectral density of the noise.Labeling Gaussian noise as 'white' describes the correlation of the noise. It is necessary to use the term "white Gaussian noise" to be correct. Gaussian noise is sometimes misunderstood tobe white Gaussian noise, but this is not the case.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

\%Gaussion noise\%
clc; close all;
clear all;
$\mathrm{N}=$ input ('enter no of samples');
R1=rand(1,N);
M=mean(R1);
v=var(R1); $x=p s d(R 1)$; subplot(2,2,1);plot(R1);
xlabel('sample numbers');ylabel('amplitude');
title('normal distributed random
signal');subplot(2,2,2);
hist(R1);
xlabel('sample numbers');ylabel('total');
title('histogram of a random signal');subplot(2,2,[3,4]);
plot(x);
xlabel('sample numbers');ylabel('amplitude');
title('psd of a normal random signal');

## OUTPUT:-

Gaussion noise
enter no of samples50

Basic Simulation Lab Manual


## RESULT: -

Additive White Gaussian noise was generated and its PSD and PDF were plotted and its Mean, Standard Deviation, Kurtosis, Skew were Computed using MATLABfunctions.

## VIVA QUESTIONS: -

1.What is a noise and how many types of noises are there?
2.What is gaussion noise?
3.What is Auto-correlation?
4.State Parseval's energy theorem for a periodic signal?
5.What is Signum function?
6. How many types of correlation are there?
7. State Parseval's Power theorem for a periodic signal?
8. What is Cross-correlation ?
9.Define ESD? Explain the relation between ESD and Auto-correlation?
10. Define PSD? Explain the relation between PSD and Auto-correlation?

## EXERCISE PROGRAMS

1. Write a MATLAB program to plot the co-sinusoidal signal.
2. Write a MATLAB program to subtract two sinusoidal signals.
3. Write a MATLAB program to subtract and multiply two sinusoidal signals.
4. Write a MATLAB program to right shift the signal to 5 times of the original signal.
5. Write a MATLAB program to left shift the signal to 8 times of the original signal.
6. Write a MATLAB program to add two different signals with $2<t<5$
7. Write a MATLAB program to shift a positive time line signal to negative timeline signal.
8. Write a MATLAB program to subtract co-sinusoidal signals.
9. Write a MATLAB program to subtract two sinusoidal signals
10. Write a MATLAB program to division and multiply two co-sinusoidal signals.
11. Write a MATLAB program to generate time scaling of a sequence.
12. Write a MATLAB program to generate time shifting of a sequence.
13. Write a MATLAB program to generate time folding of a sequence.
14. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 5.
15. Write a MATLAB program to generate time scaling of a sequence with time 2 sec.
16. Write a MATLAB program to add two different signals with $4<t<8$
17. Write a MATLAB program to shift a negative time line signal to positive timeline signal.
18. Write a MATLAB program to subtract sinusoidal signals.
19. Write a MATLAB program to subtract and divide two sinusoidal signals
20. Write a MATLAB program to add and multiply two co-sinusoidal signals.
21. Write a MATLAB program to generate time scaling of a signal.
22. Write a MATLAB program to generate time shifting of a signal.
23. Write a MATLAB program to generate time folding of a signal.
24. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 10.
25. Write a MATLAB program to generate time scaling of a sequence with time 5 sec .
26. Write a MATLAB program to compute auto correlation between

$$
\mathrm{x}=\sin \left(4^{*} \mathrm{pi}^{*} 2^{*} \mathrm{t}\right), \mathrm{y}=\sin \left(4^{*} \mathrm{pi} 20^{*} \mathrm{t}\right) \text {. and see how matlab reacts to it. }
$$

27. Write a MATLAB program to compute cross correlation between $x=\sin \left(3^{*} \mathrm{pi}^{*} 2^{*} \mathrm{t}\right), \mathrm{y}$
$=\cos \left(5^{*} \mathrm{pi}^{*} 5^{*} \mathrm{t}\right)$. and see how matlab reacts to it.
28. Write a MATLAB program to compute auto correlation between two signalsx $=4^{*} \cos \left(2^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=6^{*} \cos \left(6^{*} \mathrm{pi}^{*} 10^{*} \mathrm{t}\right)$.
29. Write a MATLAB program to compute cross correlation between two Sequences [2 648 5] \& [8 967 5].
30. Write a MATLAB program to compute auto correlation between two signals $\mathrm{x}=5^{*} \cos \left(8^{*} \mathrm{pi}{ }^{*} 10^{*} \mathrm{t}\right), \mathrm{y}=6^{*} \cos \left(7^{*} \mathrm{pi*} 10^{*} \mathrm{t}\right)$.

Basic Simulation Lab Manual

## Real Time Applications:

- Stream processing
- Vector processing
- Digital processing applications

Basic Simulation Lab Manual
EXPERMENT NO:13
SAMPLING THEORM

## AIM: -

To Demonstrate Sampling Theorem and aliasing effect using MATLAB.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

## Sampling Theorem:

The theorem shows that a band limited analog signal that has been sampled can be perfectly reconstructed from an infinite sequence of samples if the sampling rate exceeds 2 B samples per second, where $B$ is the highest frequency in the original signal.
If a signal contains a component at exactly $B$ hertz, then samples spaced at exactly $1 /(2 B)$ seconds do not completely determine the signal, Shannon's statement notwithstanding.

Proof: Let $\mathrm{g}(\mathrm{t})$ be a bandlimited signal whose bandwidth is $\mathrm{fm}(\mathrm{wm}=2 \pi \mathrm{fm})$.


Figure 2: (a) Original signal $g(t)$ (b) Spectrum $G(w)$ $\delta(\mathrm{t})$ is the sampling signal with $\mathrm{fs}=1 / \mathrm{T}>2 \mathrm{fm}$.

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(a)

Figure 3: (a) sampling signal $\delta(\mathrm{t})$ ) (b) Spectrum $\delta(\mathrm{w})$
Let $g s(t)$ be the sampled signal. Its Fourier Transform Gs(w) isgiven by

$$
\begin{aligned}
\mathcal{F}\left(g_{s}(t)\right) & =\mathcal{F}\left[g(t) \delta_{T}(t)\right] \\
& =\mathcal{F}\left[g(t) \sum_{n=-\infty}^{+\infty} \delta(t-n T)\right] \\
& =\frac{1}{2 \pi}\left[G(\omega) * \omega_{0} \sum_{n=-\infty}^{+\infty} \delta\left(\omega-n \omega_{0}\right)\right] \\
G_{s}(\omega) & =\frac{1}{T} \sum_{n=-\infty}^{+\infty} G(\omega) * \delta\left(\omega-n \omega_{0}\right) \\
G_{s}(\omega) & =\mathcal{F}\left[g(t)+2 g(t) \cos \left(\omega_{0} t\right)+2 g(t) \cos \left(2 \omega_{0} t\right)+\cdots\right] \\
G_{s}(\omega) & =\frac{1}{T} \sum_{n=-\infty}^{+\infty} G\left(\omega-n \omega_{0}\right)
\end{aligned}
$$



Figure 4: (a) sampled signal gs(t) (b) Spectrum Gs(w)
If $\omega_{s}=2 \omega_{m}$, i.e., $T=1 / 2 f_{m}$. Therefore, $G_{s}(\omega)$ is given by

$$
G_{s}(\omega)=\frac{1}{T} \sum_{n=-\infty}^{+\infty} G\left(\omega-n \omega_{m}\right)
$$

To recover the original signal $G(w)$ :

1. Filter with a Gate function, H2wm(w) of width 2wmScale it by T.

$$
G(\omega)=T G_{s}(\omega) H_{2 \omega_{m}}(\omega)
$$



Figure 5: Recovery of signal by filtering with a filter of width 2 wm

## Basic Simulation Lab Manual

## Aliasing

\{ Aliasing is a phenomenon where the high frequency components of the sampled signalinterfere with each other because of inadequate sampling ws $<2 \mathrm{wm}$.


Figure 6: Aliasing due to inadequate sampling
Aliasing leads to distortion in recovered signal. This is the reason why sampling frequency should be atleast twice thebandwidth of the signal.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

```
%sampling
theorem%
clc;
clear all; close all;
t=0:0.001:1;f=5;
x=cos(2*pi*f*t);
plot(t,x);
```

\%when fs>2fm\%
fs1=3*f; ts1=1/fs1;
n1=0:ts1:1;
xs1= $\cos \left(2^{*} \mathrm{pi}^{*} \mathrm{f}^{*} \mathrm{n} 1\right)$;
figure;
plot(n1,xs1,'r');
hold on;
plot( $\mathrm{t}, \mathrm{x}$ );
hold off;
\%when fs=2fm\%
fs2 $=2$ *f;
ts2=1/fs2;
n2=0:ts2:1;
xs2=cos(2*pi*f*n2);
figure; plot(n2,xs2,'r');
hold on;
plot(t,x);
hold off;
\%when fs<2fm\%
fs $3=1.5^{*}$ f;
ts3=1/fs3;
n3=0:ts3:1;
xs3=cos(2* $\left.\mathrm{pi}^{*} \mathrm{f}^{*} \mathrm{n} 3\right)$;
figure;
plot(n3,xs3,'r');
hold on;
plot(t,x);
hold off;

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## OUTPUT:-

sampling theorem

when fs $>2 \mathrm{fm}$


Basic Simulation Lab Manual
when fs $=2 \mathrm{fm}$

when $\mathrm{fs}<2 \mathrm{fm}$


## RESULT: -

In this experiment the sampling theorem have been verifiedusing MATLAB.

## VIVA QUESTIONS: -

1.State Paeseval's energy theorem for a periodic signal?
2. Define sampling Theorem?
3. What is Aliasing Effect?
4. what is Under sampling?
5. What is Over sampling?
6. Give the importance of Natural Sampling? 7.Give the importance of Flat-top Sampling? 8.Give the importance of ideal Sampling?
9. What is Anti-Aliasing Effect? 10.Define Stability of LTI system?

## EXERCISE PROGRAM: -

1. Write a MATLAB program to find the effect of up sampling in frequency domain.
2. Write a matlab program to get the above output where $\mathrm{t} 0=2$
3. Write a MATLAB program to find the effect of up sampling in frequency domain for 20khz.
4. Write a program to get the following output $t=-$

1: -5 5.Write mat lab program to get the above output

$$
\begin{aligned}
\mathrm{X}(\mathrm{t}) & =1 ;(0<\mathrm{t}<2) \\
& =10 ;(2<\mathrm{t}<15) \text { Note: Add ramp and unit }
\end{aligned}
$$

6.Write a matlab program to generate a sine wave with amplitude $=3$, frequency 20 Hz . $7 . \mathrm{Write}$ a matlab program to generate a cos wave with amplitude $=3$, frequency 20 Hz . 8 . Write a matlab program to generate a triangular wave with amplitude $=8$, frequency 10 Hz .
9.Write a matlab program to generate a square wave with amplitude $=2$, frequency 10 kHz .
10.Write a matlab program to generate the signum function.
11.Write a matlab program to generate exponential growing signal.
12.Write a matlab program to generate exponential decaying signal.
13.Write a matlab program to generate a triangular wave with amplitude $=6$, frequency 1 Hz .
14.Write a matlab program to generate a square wave with amplitude $=5$, frequency 5 kHz .
15.Write a matlab program to generate a sawtooth wave with amplitude $=8$, frequency 5 Khz .
16.Write a matlab program to generate a sine wave with amplitude $=5$, frequency 5 Hz .
17.Write a matlab program to generate a cos wave with amplitude $=4$, frequency 10 Hz . 18.Write a matlab program to generate a triangular wave with amplitude $=5$, frequency 4 Hz .

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19.Write a matlab program to generate a square wave with amplitude $=1$, frequency

20 kHz .20 .Write a matlab program to generate the signum function.
21.Write a matlab program to generate a square wave with amplitude $=4$, frequency 5 kHz .
22.Write a matlab program to generate a triangular wave with amplitude $=6$, frequency 6 Hz .
23.Write a matlab program to generate a triangular wave with amplitude $=8$,frequency 2Hz.
24.Write a matlab program to generate a square wave with amplitude $=7$, frequency 5 kHz .
25.Write a matlab program to generate a sawtooth wave with amplitude $=10$, frequency 10 Khz .
26.Write a matlab program to generate the step function.
27. Write a matlab program to generate exponential growing signal of amplitude $=5$. 28.Write a matlab program to generate exponential decaying signal of amplitude $=7$.. 29.Write a matlab program to generate a triangular wave with amplitude $=7$,frequency 1Hz.
30.Write a matlab program to generate a square wave with amplitude $=7$, frequency 10 kHz .

## Real Time Applications:

- Industrial control and automation (Control the velocity or position of an object)
- Examples: Controlling the position of a valve or shaft of a motor
- Examples: Digital processing applications
- TV reception
- RADAR
- SONAR


## REMOVAL OF NOISE BY AUTO CORRELATION/CROSSCORRELATION

## AIM: -

removal of noise by auto correlation/cross correlation.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

Detection of a periodic signal masked by random noise is of greate importance The noise signal encountered in practice is a signal with random amplitude variations. A signal is uncorrelated with any periodic signal. If $s(t)$ is a periodic signal and $n(t)$ is anoise signal then

## T/2 1/T

$\operatorname{Lim} \int S(t) n(t-T) d t=0$ for all $T$
T ${ }^{2} \infty$-T/2

Qsn( $T$ )= cross correlation function of $s(t)$ and $n(t)$ Then
Qsn(T)=0Detection by Auto-Correlation:
$\mathrm{S}(\mathrm{t})=$ Periodic Signal mixed with a noise signal $\mathrm{n}(\mathrm{t})$.Then $\mathrm{f}(\mathrm{t})$ is $[\mathrm{s}(\mathrm{t})+$
$\mathrm{n}(\mathrm{t})$ ]Let $\mathrm{Qff}(\mathrm{T})=$ Auto Correlation Function of $\mathrm{f}(\mathrm{t})$
Qss $(\mathrm{t})=$ Auto Correlation Function of
$\mathrm{S}(\mathrm{t}) \mathrm{Qnn}(\mathrm{T})=$ Auto Correlation Function
of $n(t)$

$$
\mathrm{T} / 2
$$

$\operatorname{Pff}(T)=\operatorname{Lim} 1 / T \int f(t) f(t-T) d t$
T-> $\quad-\mathrm{T} / 2$
T/2
$=\operatorname{Lim} 1 / \mathrm{T} \int[\mathrm{s}(\mathrm{t})+\mathrm{n}(\mathrm{t})][\mathrm{s}(\mathrm{t}-\mathrm{T})+\mathrm{n}(\mathrm{t}-\mathrm{T})]$
dtT-- $\infty$-T/2
$=\mathrm{Qss}(\mathrm{T})+\mathrm{Qnn}(\mathrm{T})+\mathrm{Q} \operatorname{sn}(\mathrm{T})+\mathrm{Qns}(\mathrm{T})$

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The periodic signal $\mathrm{s}(\mathrm{t})$ and noise signal $\mathrm{n}(\mathrm{t})$ are
uncorrelatedQsn( t$)=\mathrm{Qns}(\mathrm{t})=0$; Then

$$
\mathrm{Qff}(\mathrm{t})=\mathrm{Qss}(\mathrm{t})+\mathrm{Qnn}(\mathrm{t})
$$

The Auto correlation function of a periodic signal is periodic of the same frequency and the Auto correlation function of a non periodic signal is tends to zero for large value of $T$ since $s(t)$ is a periodic signal and $n(t)$ is non periodic signal so $\mathrm{Qss}(\mathrm{T})$ is a periodic where
as aQnn(T) becomes small for large values of T Therefore for sufficiently large values of $\operatorname{Qff}(T)$ is equal to $\mathrm{Qss}(T)$.

## Detection by Cross Correlation:

$$
\mathrm{f}(\mathrm{t})=\mathrm{s}(\mathrm{t})+\mathrm{n}(\mathrm{t})
$$

$c(t)=$ Locally generated signal with same frequencyas that of

$$
S(\mathrm{t}) \mathrm{T} / 2
$$

$\mathrm{Qfc}(\mathrm{t})=\operatorname{Lim} 1 / \mathrm{T} \int[\mathrm{s}(\mathrm{t})+\mathrm{n}(\mathrm{t})][\mathrm{c}(\mathrm{t}-\mathrm{T})] \mathrm{dt}$
T-- $\infty$-T/2
$=\mathrm{Qsc}(\mathrm{T})+\mathrm{Qnc}(\mathrm{T})$
$\mathrm{C}(\mathrm{t})$ is periodic function and uncorrelated with the random noise signal $\mathrm{n}(\mathrm{t})$.
HenceQnc(T0=0) Therefore $\mathrm{Qfc}(\mathrm{T})=\mathrm{Qsc}(\mathrm{T})$

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

\%auto
correlation\%clc;
clear all; close all; $\mathrm{t}=0: 0.1$ :pi*4;
$\mathrm{s}=\sin (\mathrm{t}) ; \mathrm{k}=2$;
subplot( $6,1,1$ ) plot(s);
title('signal s');xlabel('t');
ylabel('amplitude');n = randn([1 126]);
$\mathrm{f}=\mathrm{s}+\mathrm{n}$; subplot( $6,1,2$ ) plot(f);
title('signal $\mathrm{f}=\mathrm{s}+\mathrm{n}$ ');
xlabel('t');
ylabel('amplitude');
as=xcorr(s,s);
subplot(6,1,3);
plot(as);
title('auto correlation of s');
xlabel('t');
ylabel('amplitude'); an=xcorr(n,n);
subplot( $6,1,4$ )
plot(an);
title('auto correlation of n');xlabel('t');
ylabel('amplitude');
cff=xcorr(f,f);
subplot(6,1,5);
plot(cff);
title('auto correlation of f');
xlabel('t');
ylabel('amplitude');
hh=as+an;
subplot(6,1,6);
plot(hh);
title('addition of as+an');
xlabel('t');
ylabel('amplitude');

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clc; clear all;close all;
$\mathrm{t}=0$ :0.1:pi*4;
$\mathrm{s}=\sin (\mathrm{t}) ; \mathrm{k}=2$;
\%sk=sin(t+k);subplot(7,1,1) ;
plot(s); title('signal s');
xlabel('t');ylabel('amplitude');c=cos(t);
subplot( $7,1,2$ ) plot(c); title('signal c');xlabel('t');
ylabel('amplitude');n = randn([1 126]);
$\mathrm{f}=\mathrm{s}+\mathrm{n}$; subplot( $7,1,3$ ) plot(f);
title('signal $\mathrm{f}=\mathrm{s}+\mathrm{n}$ ');xlabel('t');
ylabel('amplitude');
asc=xcorr(s,c);
subplot(7,1,4);
plot(asc);
title('auto correlation of $s$ and $c^{\prime}$ );
xlabel('t');ylabel('amplitude'); anc=xcorr(n,c);
subplot(7,1,5)plot(anc);
title('auto correlation of $n$ and c');xlabel('t');
ylabel('amplitude'); cfc=xcorr(f,c);
subplot(7,1,6);
plot(cfc);
title('auto correlation of $f$ and $c^{\prime}$ );
xlabel('t');ylabel('amplitude');
hh=asc+anc;
subplot(7,1,7);
plot(hh);
title('addition of asc+anc'); xlabel('t');
ylabel('amplitude');

Basic Simulation Lab Manual

## OUTPUT: -

auto correlation


Basic Simulation Lab Manual


## RESULT:-

In this experiment the removal of noise by autocorrelation/cross correlation have been verified using MATLAB.

## VIVA QUESTIONS:-

1.What is Causal Signal?
2. What are the Different types of Systems?
3. What is Linear System?
4. What is Signum function?
5. What is Static and Dynamic System?
6. Define Linear Convolution?
7. Define Properties of Convolution in time domain?
8. What is the Difference Between Linear Convolution\& Circular Correlation?
9. What are Dirchlet Conditions for Fourier Transform?
10.What is Full Wave Symmetry?

## EXERCISE PROGRAMS

1. Write a MATLAB program to find the cross correlation using FFT.
2. Write a mat lab program to perform the cross correlation between sinusoidal and rampfunction and see how mat lab reacts to it.
3. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
4. Write a MATLAB program to perform cross correlation between sinusoidal and ramp signaland see how mat lab reacts to it.
5. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 2 & 3\end{array}\right]$ and $y$ ( n ) $=[-1-2]$ and see how matlab reacts to it.
6. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{ll}1-3 & 5\end{array}\right]$ and $y$ (n) = [llllll $\left.123 \begin{array}{ll}1\end{array}\right]$ and see how matlab reacts to it.
7. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 0 & 1\end{array}\right]$ and $y$ (n) = $\left.\begin{array}{llll}1 & 0 & 0 & 0\end{array}\right]$ and see how matlab reacts to it.
8. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lllll}1 & 1 & 1 & 1 & 0\end{array} 00000\right]$ and $y(n)=\left[\begin{array}{lllll}1 & 0 & 1 & 0 & 1\end{array} 010\right]$ and see how matlab reacts to it.
9. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array}\right]$ and $y(n)$ = $\left.\begin{array}{llll}1 & 1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.
10. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{ll}6789 & 10\end{array}\right]$ andy ( n ) = [ $\left.\begin{array}{llll}5 & 4 & 3 & 2\end{array}\right]$ ] and see how matlab reacts to it.
11. Write the MATLAB program to perform cross correlation between the following sequencesX(n)=[2-2 32 , $h(n)=\left[\begin{array}{lll}-2 & 4 & -5\end{array}\right]$.

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12. Write a mat lab program to perform the convolution between step and ramp function and seehow mat lab reacts to it.
13. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
14. Write a MATLAB program to perform convolution between sinusoidal and square signal andsee how mat lab reacts to it.
15. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 3 & 4\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{cc}-2 & -4\end{array}\right]$ and see how matlab reacts to it.
16. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}3 & -4 \\ 6\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{lll}2 & 6 & 8\end{array}\right]$ and see how matlab reacts to it.
17. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}3 & 1 & 2\end{array} 0\right]$ and $y$
(n) $=\left[\begin{array}{lll}2 & 4 & 3\end{array} 4\right.$ 5 $]$ and see how matlab reacts to it.
18. Write a MATLAB program to perform the convolution between $X(n)=[22102110]$ and $y(n)=\left[\begin{array}{llllll}1 & 1 & 1 & 2 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
19. Write a MATLAB program to perform the convolution between $\mathrm{X}(\mathrm{n})=\left[\begin{array}{lll}2 & 1 & 2\end{array} 1\right.$ 1] and $y$
(n) $=\left[\begin{array}{llll}1 & 2 & 1 & 2\end{array}\right]$ and see how matlab reacts to it.
20. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}5 & 6 & 9 \\ 8\end{array}\right]$ and $y(n)$ = [1 2321 1] and see how matlab reacts to it.
21. Write the MATLAB program to perform cross correlation between the following sequences $X(n)=\left[\begin{array}{llll}4 & -6 & 5 & 1\end{array}\right], h(n)=\left[\begin{array}{llll}-1 & 3 & -4 & 3\end{array}\right]$.
22. Write a mat lab program to perform the cross correlation between ramp and step function andsee how mat lab reacts to it.
23. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
24. Write a MATLAB program to perform cross correlation between sinusoidal and step signaland see how mat lab reacts to it.
25. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 5 & 6\end{array}\right]$ and $y$
$(\mathrm{n})=[-3-6]$ and see how matlab reacts to it.
26. Write a MATLAB program to plot the co-sinusoidal signal.
27. Write a MATLAB program to subtract two sinusoidal signals.
28. Write a MATLAB program to subtract and multiply two sinusoidal signals.
29. Write a MATLAB program to right shift the signal to 5 times of the original signal.
30. Write a MATLAB program to left shift the signal to 8 times of the original signal.

## Real Time Applications:

- The cross correlation is to determine the response $y[n]$ of a system of a known impulseresponse $\mathrm{h}[\mathrm{n}]$ for a given input signal $\mathrm{x}[\mathrm{n}]$ to obtain $\mathrm{y}[\mathrm{n}]$. Digital signal processing applications etc...


## EXPERMENT NO:15

## EXTRACTION OF PERIODIC SIGNAL MASKED BY NOISE USING CORRELATION

## AIM: -

To generate a periodic sequence, corrupt it with zero mean White noise and extract the sequence using periodic circular cross correlation.

## SOFTWARE REQURIED:-

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY: -

Removal of noise by Filtering is not the solution because noise contains power at allfrequencies. Hence we use correlation techniques.

The theorem is useful for analyzing linear time-invariant systems, LTI systems, when the inputs and outputs are not square integrable, so their Fourier transforms do not exist. A corollary is that the Fourier transform of the autocorrelation function of the output of an LTI system is equal to the product of the Fourier transform of the autocorrelation function of the input of the system times the squared magnitude of the Fourier transform of the system impulse response. This works even when the Fourier transforms of the input and output signals do not exist because these signals are not square integrable, so the system inputs and outputs cannot be directly related by the Fourier transform of the impulse response. Since the Fourier transform of the autocorrelation function of a signal is the power spectrum of the signal, this corollary is equivalent to saying that the power spectrum of the output is equal to the power spectrum of the input times the power transfer function. This corollary is used in the parametric method for power spectrum estimation.

PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

clc;
clear
all;close
all;
n=256;
k1=0:n-1;
$\mathrm{x}=\cos \left(32^{*} \mathrm{pi}^{*} \mathrm{k} 1 / \mathrm{n}\right)+\sin \left(48^{*} \mathrm{pi}{ }^{*} \mathrm{k} 1 / \mathrm{n}\right)$;
plot(k1,x);
\%Module to find period of input
signalk=2;
xm=zeros(k,1);ym=zeros(k,1);hold on;
for $\mathrm{i}=1$ :k
[xm(i) ym(i)]=ginput(1);
plot(xm(i),
ym(i),'r*');end;
period=abs(xm(2)-xm(1));
rounded_p=round(period); m=rounded p;
\% Adding noise and plotting noisy
signaly=x+randn(1,n);
figure; plot(k1,y);
\% To generate impulse train with the period as that of input
signal\%d=zeros(1,n);
for $\mathrm{i}=1$ : n
if $($ rem $(i-1, m)==0) d(i)=1$;
end; end;
\% correlating noisy signal and impulse
traincir=cxcorr1(y,d);
\%plotting the original and reconstructed
signalm1=0:n/4;
figure
plot(m1,x(m1+1),'r',m1,m*cir(m1+1));

## OUTPUT:-




## RESULT:-

Using Cross- correlation the periodic signal from noise was estimated usingMATLAB.

## VIVA QUESTIONS: -

1. State the relationship between PSD and ACF?
2. What is the integration of ramp signal?
3. Difference between vectors and signals?
4. What is the important of dot product over cross product in signals?
5. Define Hilbert transforms?
6. What is Hilbert transform of $\operatorname{Sin}(\mathrm{t})$ ?
7. What is Hilbert transform of $\operatorname{Cos}(\mathrm{t})$ ?
8. What is difference between Hilbert transforms and Fourier Transforms? 9.What is difference between Hilbert transforms and Laplace Transforms?10.Explain LTI and LTV systems?

## EXERCISE PROGRAM:-

1.Simulate a matlab program on autocorrelation and PSD if $x=\left[\begin{array}{llll}1 & 2 & 3 & 4\end{array}\right.$ 5.
2. Write a mat lab program to perform the cross correlation between sinusoidal and rampfunction and see how mat lab reacts to it.
3. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
4. Write a MATLAB program to perform cross correlation between sinusoidal and ramp signaland see how mat lab reacts to it.
5. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 2 & 3\end{array}\right]$ and $y$ $(\mathrm{n})=[-1-2]$ and see how matlab reacts to it.
6. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{ll}1-35\end{array}\right]$ and $y$ (n) = $\left.\begin{array}{lll}1 & 2 & 3\end{array}\right]$ ] and see how matlab reacts to it.
7. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 0 & 1\end{array} 1\right]$ and $y$ (n) = $\left.\begin{array}{llll}1 & 0 & 0 & 0\end{array}\right]$ and see how matlab reacts to it.
8. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{llllll}1 & 1 & 1 & 1 & 0 & 0\end{array} 0000\right]$ and $y(n)=\left[\begin{array}{llllll}1 & 0 & 1 & 0 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
9.Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array} 0\right]$ and $y(n)$ = $\left[\begin{array}{llll}1 & 1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.
10. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{ll}678 & 9 \\ 10\end{array}\right]$ andy ( n ) $=\left[\begin{array}{llll}5 & 4 & 3 & 2\end{array}\right]$ and see how matlab reacts to it.
11. Write the MATLAB program to perform cross correlation between the following sequences $X(n)=\left[\begin{array}{lll}2 & -2 & 3 \\ 2\end{array}, h(n)=\left[\begin{array}{lll}-2 & 4 & -5\end{array}\right]\right.$.
12. Write a mat lab program to perform the convolution between step and ramp function and seehow mat lab reacts to it.
13. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
14. Write a MATLAB program to perform convolution between sinusoidal and square signal andsee how mat lab reacts to it.
15. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 3 & 4\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{ll}-2 & -4\end{array}\right]$ and see how matlab reacts to it.
16. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}3 & -4 \\ 6\end{array}\right]$ and $y$
(n) $=\left[\begin{array}{lll}2 & 6 & 8\end{array} 6\right.$ and see how matlab reacts to it.

## Basic Simulation Lab Manual

17. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}3 & 1 & 2\end{array} 0\right]$ and $y$ (n) $=\left[\begin{array}{lll}2 & 4 & 4\end{array}\right.$ 5] and see how matlab reacts to it.
18. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}2 & 2102110]\end{array}\right]$ and $y(n)=\left[\begin{array}{llllll}1 & 1 & 1 & 2 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
19. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 1 & 2\end{array} 1\right]$ and $y$

20. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}5 & 6 & 9 \\ 8\end{array}\right]$ and $y(n)$ = [1 2321 1] and see how matlab reacts to it.
21. Write the MATLAB program to perform cross correlation between the following sequences $X(n)=\left[\begin{array}{llll}4 & -6 & 5 & 1\end{array}\right], h(n)=\left[\begin{array}{lll}-1 & 3 & -4\end{array}\right]$.
22. Write a mat lab program to perform the cross correlation between ramp and step function andsee how mat lab reacts to it.
23. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
24. Write a MATLAB program to perform cross correlation between sinusoidal and step signaland see how mat lab reacts to it.
25. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}1 & 5 & 6\end{array}\right]$ and $y$ (n) $=[-3-6]$ and see how matlab reacts to it.
26. Write a MATLAB program to find Hilbert transforms of the causal signal $x(t)=t \wedge 2$
27. Write a MATLAB program to find Hilbert transforms of the causal signal $x(t)=t$
28. Write a MATLAB program to find Hilbert transforms of the causal signal $x(t)=e^{\wedge}$-at
29. Write a MATLAB program to find Hilbert transforms of the causal signal $x(t)=e^{\wedge}$ at
30. Write a MATLAB program to find Hilbert transforms of the causal signal $x(t)=t e^{\wedge}$ at

## Real Time Applications:

- The cross correlation is to determine the response $y[n]$ of a system of a known impulseresponse $h[n]$ for a given input signal $x[n]$ to obtain $y[n]$.
- Digital signal processing applications etc...
- TV reception.

Basic Simulation Lab Manual
EXPERMENT NO:16

## VERIFICATION OF WIENER-KHINCHIN RELATION

## AIM: -

Verification of wiener-khinchine relation.

## SOFTWARE REQURIED: -

## 1.MATLAB R2010a.

2.Windows XP SP2.

## THEORY:-

The Wiener-Khinchin theorem (also known as the Wiener-Khintchine theorem and sometimes as the Wiener-Khinchin-Einstein theorem or the Khinchin-Kolmogorov theorem) states that the power spectral density of a wide-sense-stationary random process is the Fourier transform of the corresponding autocorrelation function.
Continuous case:

$$
S_{x x}(f)=\int_{-\infty}^{\infty} r_{x x}(\tau) e^{-j 2 \pi f \tau} d \tau
$$

## Where

$$
r_{x x}(\tau)=\mathrm{E}\left[x(t) x^{*}(t-\tau)\right]
$$

is the autocorrelation function defined in terms of statistical expectation, and where is thepower spectral density of the function. Note that the autocorrelation function is defined in terms of the expected value of a product, and that the Fourier transform of does not exist in general, because stationary random functions are not square integrable.
The asterisk denotes complex conjugate, and can be omitted if the random process is real valued.

## Discrete case:

$$
S_{x x}(f)=\sum_{k=-\infty}^{\infty} r_{x x}[k] e^{-j 2 \pi k f}
$$

where

$$
r_{x x}[k]=\mathrm{E}\left[x[n] x^{*}[n-k]\right]
$$

and where is the power spectral density of the function with discrete values. Being asampled and discrete-time sequence, the spectral density is periodic in the frequencydomain.

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## PROGRAM:-

\% wiener-khinchine relation\%
clc;
clear all; $\mathrm{t}=0: 0.1: 2^{*} \mathrm{pi} ; \mathrm{x}=\sin \left(2^{*} \mathrm{t}\right)$; subplot( $3,2,1$ );
$\operatorname{plot}(\mathrm{x})$; $\mathrm{au}=\mathrm{xcorr}(\mathrm{x}, \mathrm{x})$;
subplot(3,2,2);
plot(au);
v=fft(au); subplot(3,2,3);
plot(abs(v)); fw=fft(x);
subplot( $3,2,4$ ); plot(fw);
fw2=(abs(fw)).^2;
subplot(3,2,5);
plot(fw2);

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## OUTPUT:-

wiener-khinchine relation


## RESULT:-

Calculation of Auto-correlation function using Weiner-Khinchin theorm was verifiedusing MATLAB.

## VIVA QUESTIONS: -

1. What is mean wiener-khinchine relation?
2. Define fourier transform and its inverse?
3. What is the difference $b / w$ convolution and correlation?
4. What is the importance of power spectrum?
5. What is the importance of correlation?
6. Write the relation between Step and Impulse signals?
7. Write the relation between Ramp and impulse signals?
8. Write the relation between Ramp and Step signals?
9. Define Standerd signals?
10. Give examples of Standerd signals?

## EXERCISE PROGRAMS

1.Write a MATLAB program to illustrate the effect of anti-aliasing filter.
2. Write a MATLAB program to subtract two sinusoidal signals.
3. Write a MATLAB program to subtract and multiply two sinusoidal signals.
4. Write a MATLAB program to right shift the signal to 5 times of the original signal.
5. Write a MATLAB program to left shift the signal to 8 times of the original signal.
6. Write a MATLAB program to add two different signals with $2<t<5$
7. Write a MATLAB program to shift a positive time line signal to negative timeline signal
8. Write a MATLAB program to subtract co-sinusoidal signals.
9. Write a MATLAB program to subtract two sinusoidal signals
10. Write a MATLAB program to division and multiply two co-sinusoidal signals.
11. Write a MATLAB program to generate time scaling of a sequence.
12. Write a MATLAB program to generate time shifting of a sequence.
13. Write a MATLAB program to generate time folding of a sequence.
14. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 5.
15. Write a MATLAB program to generate time scaling of a sequence with time 2 sec.
16. Write a MATLAB program to add two different signals with $4<t<8$
17. Write a MATLAB program to shift a negative time line signal to positive timeline signal.
18. Write a MATLAB program to subtract sinusoidal signals.

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19. Write a MATLAB program to subtract and divide two sinusoidal signals
20. Write a MATLAB program to add and multiply two co-sinusoidal signals.
21. Write a MATLAB program to generate time scaling of a signal.
22. Write a MATLAB program to generate time shifting of a signal.
23. Write a MATLAB program to generate time folding of a signal.
24. Write a MATLAB program to generate amplitude scaling of a sequence with amplitude 10.
25. Write a MATLAB program to generate time scaling of a sequence with time 5 sec.
26. Find the addition of null matrix and unity matrix of order $4 x 4$.
27. Write a MATLAB program to find rank of the matrixA= [64 93 5; 6248 5; 6317 9].
28. Write a MATLAB program to find Eigen of the matrixA= [2 503 4; 5437 8; 9165 4].
29. Write a MATLAB program to find inverse of the matrixA=[15985;43584; 56350 0]
30. Write a MATLAB program to find determinant of the matrixA= [16 68 5; $93564 ; 1635$ 6].

## Real Time Applications:

- Stream processing applications
- Block processing applications
- Vector processing applications
- Signal processing applications


## CHECKING A RANDOM PROCESS FOR STATIONARITY IN WIDE SENSE.

AIM: - Checking a random process for stationarity in wide sense.

## SOFTWARE REQURIED:-

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY:-

A stationary process (or strict(ly) stationary process or strong(ly) stationary process) is a stochastic process whose joint probability distribution does not change when shifted in time orspace. As a result, parameters such as the mean and variance, if they exist, also do not changeover time or position. Weak or wide-sense stationary A weaker form of stationary commonly employed in signal processing is known as weak-sense stationary, wide-sense stationarity (WSS)or covariance stationarity. WSS random processes only require that 1 st and 2nd moments do notvary with respect to time.

$$
\mathbb{E}\{x(t)\}=m_{x}(t)=m_{x}(t+\tau) \forall \tau \in \mathbb{R}
$$

and autocorrelation function

$$
\mathbb{E}\left\{x\left(t_{1}\right) x\left(t_{2}\right)\right\}=R_{x}\left(t_{1}, t_{2}\right)=R_{x}\left(t_{1}+\tau, t_{2}+\tau\right)=R_{x}\left(t_{1}-t_{2}, 0\right) \forall \tau \in \mathbb{R}
$$

The first property implies that the mean function $\mathrm{mx}(\mathrm{t})$ must be constant. The second property implies that the correlation function depends only on the difference between t 1 and t2 and only needs to be indexed by one variable rather than two variables. Thus, instead of writing,
$\mathrm{Rx}(\mathrm{t} 1-\mathrm{t} 2,0)$ we usually abbreviate the notation and write

$$
R_{x}(\tau) \text { where } \tau=t_{1}-t_{2}
$$

This also implies that the auto covariance depends only on $=\mathrm{t} 1-\mathrm{t} 2$, since

$$
C_{x}\left(t_{1}, t_{2}\right)=C_{x}\left(t_{1}-t_{2}, 0\right)=C_{x}(\tau)
$$

## Stationary and Non Stationary Random Process:

A random $\mathrm{X}(\mathrm{t})$ is stationary if its statistical properties are unchanged by a time shift in the time

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origin. When the auto-Correlation function $R x(t, t+T)$ of the random $X(t)$ varies with
time difference $T$ and the mean value of the random variable $X(t 1)$ is independent of the choicet1, then $\mathrm{X}(\mathrm{t})$ is said to be stationary in the wide sense or wide-sense stationary. So a continuous- Time random process $\mathrm{X}(\mathrm{t})$ which is WSS has the following properties

1) $E[X(t)]=\mu X(t)=\mu X(t+T)$
2) The Autocorrelation function is written as a function of $T$
that isRX( $\mathrm{t}, \mathrm{t}+\mathrm{T})=\mathrm{Rx}(\mathrm{T})$
If the statistical properties like mean value or moments depends on time then the random processis said to be non-stationary.

When dealing with two random process $\mathrm{X}(\mathrm{t})$ and $\mathrm{Y}(\mathrm{t})$, we say that they are jointly widesensestationary if each process is stationary in the wide-sense.

$$
\operatorname{Rxy}(\mathrm{t}, \mathrm{t}+\mathrm{T})=\mathrm{E}[\mathrm{X}(\mathrm{t}) \mathrm{Y}(\mathrm{t}+\mathrm{T})]=\mathrm{Rxy}(\mathrm{~T})
$$

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window

```
PROGRAM:-
Clc; Close all;
clear all
y = randn([1 40]) my=round(mean(y));
z=randn([1 40]) mz=round(mean(z));
vy=round(var(y));
vz=round(var(z));
t = sym('t','real');h0=3;
x=y.*}\operatorname{sin}(\textrm{h}0*\textrm{t})+\textrm{z}.**\operatorname{cos}(\textrm{h}0*\textrm{t})
mx=round(mean(x));
k=2;
xk=y.*}\operatorname{sin}(\textrm{h}0*(\textrm{t}+\textrm{k}))+\textrm{z}.**\operatorname{cos}(\textrm{h}0*(\textrm{t}+\textrm{k}));\textrm{x}1=\operatorname{sin}(\textrm{h}\mp@subsup{0}{}{*}\textrm{t})*\operatorname{sin}(\textrm{h}0*(\textrm{t}+\textrm{k}));\textrm{x}2=\operatorname{cos}(\textrm{h}0*\textrm{t})**\operatorname{cos}(\textrm{h}0*(\textrm{t}+\textrm{k}))
c=vy*x1+vz*x1;
```


## OUTPUT:

\%if we solve " $\mathrm{c}=2^{*} \sin \left(3^{*} \mathrm{t}\right) * \sin \left(3^{*} \mathrm{t}+6\right)$ " we get $\mathrm{c}=2 \cos (6)$
$\%$ which is a costant does not depent on variable ' $t$ '
$\%$ so it is wide sence stationary.

## RESULT:-

Checking a random process for stationarity in wide sense by using MATLAB .

## VIVA QUESTIONS:-

1. what is the condition for WSS random process?2.Define random variable with examples?
2. Define random process with examples?
3. Difference between ACF and CCF?
4. what are the different noises?
5. Explain two Properties of Auto-Correlation?
6. Explain two Properties of Cross-Correlation?
7. What is the difference b/w Auto-correlation and Cross-

Correlation?9.Define ESD?
10.Define PSD?

## EXERCISE PROGRAMS

1. Write a program to simulate parseval's relation
2. Write a mat lab program to perform the cross correlation between sinusoidal and rampfunction and see how mat lab reacts to it.
3. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
4. Write a MATLAB program to perform cross correlation between sinusoidal and ramp signaland see how mat lab reacts to it.
5. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 2 & 3\end{array}\right]$ and $y$ ( n ) $=[-1-2]$ and see how matlab reacts to it.
6. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{ll}1-35\end{array}\right]$ and $y$ (n) = [lllllllll 12344 and see how matlab reacts to it.
7. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 0 & 1\end{array} 1\right]$ and $y$ (n) = $\left.\begin{array}{llll}1 & 0 & 0 & 0\end{array}\right]$ ] and see how matlab reacts to it.
8. Write a MATLAB program to perform the cross correlation between $\mathrm{X}(\mathrm{n})=\left[\begin{array}{lllll}111 & 1 & 0 & 0 & 0\end{array}\right]$ and $y(n)=\left[\begin{array}{lllll}1 & 0 & 1 & 0 & 1\end{array} 010\right]$ and see how matlab reacts to it.
9. Write a MATLAB program to perform the cross correlation between $X(n)=\left[\begin{array}{lll}1 & 1 & 0\end{array} 0\right]$ and $y(n)$ = $\left.\begin{array}{llll}1 & 1 & 1 & 1\end{array}\right]$ and see how matlab reacts to it.
10. Write a MATLAB program to perform the cross correlation between X (n) = [678910]

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andy (n) = [54 4321 1] and see how matlab reacts to it.
11. Write the MATLAB program to perform cross correlation between the following sequencesX(n)=[2-2 32 , h(n) $=\left[\begin{array}{lll}-2 & 4 & -5\end{array}\right]$.
12. Write a mat lab program to perform the convolution between step and ramp function and seehow mat lab reacts to it.
13. Write a MATLAB program to perform convolution between square and step signal and seehow mat lab reacts to it.
14. Write a MATLAB program to perform convolution between sinusoidal and square signal andsee how mat lab reacts to it.
15. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}2 & 3 \\ 4 & 5\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{cc}-2 & -4\end{array}\right]$ and see how matlab reacts to it.
16. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}3-4 & 6\end{array}\right]$ and $y$ (n) $=\left[\begin{array}{lll}2 & 6 & 8\end{array}\right]$ and see how matlab reacts to it.
17. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}3 & 1 & 2\end{array} 0\right]$ and $y$ (n) $=\left[\begin{array}{lll}2 & 4 & 3\end{array} 4\right.$ 5] and see how matlab reacts to it.
18. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}2 & 102110\end{array}\right]$ and $y(n)=\left[\begin{array}{llllll}1 & 1 & 1 & 2 & 1 & 0\end{array} 10\right]$ and see how matlab reacts to it.
19. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}2 & 1 & 2\end{array} 1\right]$ and $y$ ( n ) $=\left[\begin{array}{llll}1 & 2 & 1 & 2\end{array}\right]$ and see how matlab reacts to it.
20. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{lll}5 & 6 & 8\end{array}\right]$ and $y(n)$ = [1 2321 1] and see how matlab reacts to it.
21. Write the MATLAB program to perform cross correlation between the following sequences $X(n)=\left[\begin{array}{llll}4 & -6 & 5 & 1\end{array}\right], h(n)=\left[\begin{array}{lll}-1 & 3 & -4\end{array}\right]$.
22. Write a mat lab program to perform the cross correlation between ramp and step function andsee how mat lab reacts to it.
23. Write a MATLAB program to perform cross correlation between square and step signal andsee how mat lab reacts to it.
24. Write a MATLAB program to perform cross correlation between sinusoidal and step signaland see how mat lab reacts to it.
25. Write a MATLAB program to perform the convolution between $X(n)=\left[\begin{array}{ll}1 & 5 \\ 6 & 5\end{array}\right]$ and $y$ (n) $=[-3-6]$ and see how matlab reacts to it.
26. Write a MATLAB program to illustrate the effect of anti-aliasing filter.
27. Write a MATLAB program to subtract two sinusoidal signals.
28. Write a MATLAB program to subtract and multiply two sinusoidal signals.
29. Write a MATLAB program to right shift the signal to 2 times of the original signal.
30. Write a MATLAB program to left shift the signal to 5 times of the original signal.

## Real Time Applications:

- Parseval's theorem for energy signals
- Parseval's theorem for power signals
- Digital signal processing applications etc...


# LOCATING THE ZEROS AND POLES AND PLOTTING THE POLE ZERO MAPS IN S-PLANE AND Z-PLANE FOR THE GIVENTRANSFER FUNCTION. 

AIM: -
To locating the zeros and poles and plotting the pole zero maps in s-plane and z-plane for the given transfer function.

## SOFTWARE REQURIED: -

1.MATLAB R2010a.
2.Windows XP SP2.

## THEORY:-

A Transfer Function is the ratio of the output of a system to the input of a system,in the Laplace domain considering its initial conditions to be zero. If we have an input function of $\mathrm{X}(\mathrm{s})$, and an output function $\mathrm{Y}(\mathrm{s})$, we define the transfer function $\mathrm{H}(\mathrm{s})$ to be:

$$
H(s)=\frac{Y(s)}{X(s)}
$$

transfer function is the Laplace transform of a system"s impulse response.


Given a continuous-time transfer function in the Laplace domain, $H(s)$ or a discrete-time onein the Z-domain, $H(z)$, a zero is any value of $s$ or $z$ such that the transfer function is zero, and a pole is any value of $s$ or $z$ such that the transfer function is infinite.

Zeros:1. The value(s) for $z$ where the numerator of the transfer function equals zero2. The complex frequencies that make the overall gain of the filter transfer functionzero.

Poles: 1. The value(s) for $z$ where the denominator of the transfer function equals zero 2 . The complex frequencies that make the overall gain of the filter transfer functioninfinite.

## Z-transforms

the Z-transform converts a discrete time-domain signal, which is a sequence of real or complex numbers, into a complex frequency-domain representation. The Z-transform, likemany other integral transforms, can be defined as either a one-sided or two-sided transform.

## Bilateral Z-transform

The bilateral or two-sided Z-transform of a discrete-time signal $\mathrm{x}[\mathrm{n}]$ is the function $\mathrm{X}(\mathrm{z})$ defined as

$$
X(z)=\mathcal{Z}\{x[n]\}=\sum_{n=-\infty}^{\infty} x[n] z^{-n}
$$

## Unilateral Z-transform

Alternatively, in cases where $x[n]$ is defined only for $n \geq 0$, the single-sided or unilateralZtransform is defined as

$$
X(z)=\mathcal{Z}\{x[n]\}=\sum_{n=0}^{\infty} x[n] z^{-n}
$$

In signal processing, this definition is used when the signal is causal.
where $z=r \cdot e^{j \omega}$

$$
X(z)=\frac{P(z)}{Q(z)}
$$

The roots of the equation $P(z)=0$ correspond to the 'zeros' of $X(z)$ The roots of the equation $Q(z)=0$ correspond to the 'poles' of $X(z)$

## PROCEDURE:-

- Open MATLAB
- Open new M-file
- Type the program
- Save in current directory
- Compile and Run the program
- For the output see command window $\backslash$ Figure window


## Basic Simulation Lab Manual

## PROGRAM:-

## \%locating poles of zero on s-plane\%

clc;
clear all;
close all;
num=input('enter numerator co-efficients');
den=input('enter denominator co-efficients');h=tf(num,den);
poles=roots(den); zeros=roots(num);sgrid;
pzmap(h);
grid on;
title('locating poles of zeros on s-plane');
\%locating poles \&zeros on $\mathrm{z}^{-}$
plane\%
clc;
clear all;close all;
num=input('enter numerator coefficient'); den=input('enter denominator coefficient'); $\mathrm{p}=$ roots(den);
z=roots(num);zplane(p,z); grid;
title('locating poler and zeros on s-plane');

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## OUTPUT: -

locating poles of zero on s-plane

enter denominator coefficient[ 76 5]

locating poles \&zeros on z-plane
enter numerator coefficient [1 2 3]


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## RESULT: -

In this experiment the zeros and poles and plotting the pole zeromaps in s-plane and z-plane for the given transfer function using MATLAB.

## VIVA QUESTIONS: -

1.Study the details of ztrans() and iztrans() functions?
2.What are poles and zeros?
3.How you specify the stability based on poles and zeros?
4.Define S-plane and Z-plane?
5.What is the difference b/w S-plane and Z-plane?6.Define Scaling Property of Z-plane?
7. Explain Time Convolution Property of Z-plane?
8. Explain Frequency Convolution Property of Z-plane
9. Explain the linearity property of Z-plane?10.Describe the advantages of Z-plane?

## EXERCISE PROGRAMS

1. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-5 y(n-1)+4 y(n-2)=x(n)-2 x(n-1)$.
2. Write a MATLAB program to find the impulse response of the following difference equation $6 y(n)-9 y(n-1)-4 y(n-2)=x(n)-5 x(n-1)$.
3. Write a MATLAB program to find the impulse response of the following difference equation8y(n)-6y(n-1)+4y(n-2)=x(n)+2x(n-1).
4. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)+5 y(n-1)+9 y(n-2)=x(n)-9 x(n-1)$.
5. Write a MATLAB program to find the impulse response of the following difference equation6y(n)-5y(n-1)+4y(n-2)=x(n)-2x(n-1).
6. Write a MATLAB program to find the impulse response of the following difference equation7y(n)-5y(n-1)+4y(n-2)=x(n)-9x(n-1).
7. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-5 y(n-1)+4 y(n-2)=x(n)-6 x(n-1)$.
8. Write a MATLAB program to find the impulse response of the following difference equation5y(n)-5y(n-1)+5y(n-2)=x(n)-2x(n-1).
9. Write a MATLAB program to find the impulse response of the following difference equation3y(n)-6 y(n-1)+4y(n-2)=x(n)-7x(n-1).
10. Write a MATLAB program to find the impulse response of the following difference equation $2 y(n)-5 y(n-1)+4 y(n-2)=x(n)-2 x(n-1)$.
11. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-5 y(n-1)+4 y(n-2)=5 x(n)-6 x(n-1)$.
12. Write a MATLAB program to find the impulse response of the following difference equation6y(n)-8y(n-1)-4y(n-2)=7x(n)-5x(n-1).
13. Write a MATLAB program to find the impulse response of the following difference equation8y(n)-8y(n-1)+9y(n-2)=x(n)+5x(n-1).
14. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)+9 y(n-1)+9 y(n-2)=9 x(n)-5 x(n-1)$.
15. Write a MATLAB program to find the impulse response of the following difference equation6y(n)-5y(n-1)+4y(n-2)=7x(n)-2x(n-1).
16. Write a MATLAB program to find the impulse response of the following difference equation7y(n)-5y(n-1)+4y(n-2)=x(n)-7x(n-1).
17. Write a MATLAB program to find the impulse response of the following difference equation3y(n)-5y(n-1)+4y(n-2)=x(n)-6x(n-1).
18. Write a MATLAB program to find the impulse response of the following difference equation $5 y(n)-5 y(n-1)+5 y(n-2)=7 x(n)-2 x(n-1)$.
19. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-6 y(n-1)+4 y(n-2)=4 x(n)-x(n-1)$.
20. Write a MATLAB program to find the impulse response of the following difference equation $2 y(n)-5 y(n-1)+4 y(n-2)=x(n)-2 x(n-1)$.
21. Write a MATLAB program to find the impulse response of the following difference equation

$$
7 y(n)-5 y(n-1)+y(n-2)=x(n)-7 x(n-1)
$$

22. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-5 y(n-1)+4 y(n-2)=x(n)-6 x(n-1)+u(n)$
23. Write a MATLAB program to find the impulse response of the following difference equation $5 y(n)-5 y(n-1)+5 y(n-2)=7 x(n)-2 x(n-1)+u(n)$.
24. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-6 y(n-1)+4 y(n-2)=4 x(n)-x(n-1)+u(n)$.
25. Write a MATLAB program to find the impulse response of the following difference equation $2 y(n)-5 y(n-1)+4 y(n-2)=x(n)-2 x(n-1)+u(n)$.
26. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)-5 y(n-1)+4 y(n-2)=4 x(n)-12 x(n-1)$.
27. Write a MATLAB program to find the impulse response of the following difference equation $6 y(n)-9 y(n-1)-4 y(n-2)=6 x(n)-15 x(n-1)$.
28. Write a MATLAB program to find the impulse response of the following difference equation $8 y(n)-6 y(n-1)+4 y(n-2)=8 x(n)+2 x(n-1)$.
29. Write a MATLAB program to find the impulse response of the following difference equation $3 y(n)+5 y(n-1)+9 y(n-2)=5 x(n)-9 x(n-1)$.
30. Write a MATLAB program to find the impulse response of the following difference equation $6 y(n)-5 y(n-1)+4 y(n-2)=x(n)-6 x(n-1)$.

## Real Time Applications:

Z- Transforms having following
applicationsAnalysis of differential
equations
Z- transform
spectroscopyQuantum
mechanics
Signal processing applications etc
Conversion of analog signals to digital signals etc

